# On Common Fixed Point Theorems for Occasionally Weakly Compatible Mappings in Menger Space 

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#### Abstract

In this paper, the concept of occasionally weak compatibility in Menger space has been applied to prove a common fixed point theorem for six self maps. Our result generalizes and extends the result of Pathak and Verma [1].


Keywords: Probabilistic metric space, Menger space, common fixed point, compatible maps, occasionally weak compatibility.
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## 1. Introduction

There have been a number of generalizations of metric space. One such generalization is Menger space initiated by Menger [2]. It is a probabilistic generalization in which we assign to any two points x and y , a distribution function $\mathrm{F}_{\mathrm{x}, \mathrm{y}}$. Schweizer and Sklar [3] studied this concept and gave some fundamental results on this space. Sehgal and Bharucha-Reid [4] obtained a generalization of Banach Contraction Principle on a complete Menger space which is a milestone in developing fixed-point theory in Menger space.
Recently, Jungck and Rhoades [5] termed a pair of self maps to be coincidentally commuting or equivalently weakly compatible if they commute at their coincidence points. Sessa [6] initiated the tradition of improving commutativity in fixed-point theorems by introducing the notion of weak commuting maps in metric spaces. Jungck [7] soon enlarged this concept to compatible maps. The notion of compatible mapping in a Menger space has been introduced by Mishra [8]. In the sequel, Pathak and Verma [1] proved a common fixed point theorem in Menger space using compatibility and weak compatibility. Using the concept of compatible mappings of type (A), Jain et. al. [9, 10] proved some interesting fixed point theorems in Menger space. Afterwards, Jain et. al. [11] proved the fixed point theorem using the concept of weak compatible maps in Menger space.

In this paper a fixed point theorem for six self maps has been proved using the concept of occasionally weak compatibility which turns out to be a material generalization of the result of Pathak and Verma [1].

## 2. Preliminaries

Definition 2.1. A mapping $\mathcal{F}: \mathrm{R} \rightarrow \mathrm{R}^{+}$is called a distribution if it is non-decreasing left continuous with

$$
\inf \{F(t) \mid t \in R\}=0 \quad \text { and } \quad \sup \{F(t) \mid t \in R\}=1
$$

We shall denote by L the set of all distribution functions while H will always denote the specific distribution function defined by $H(t)=\left\{\begin{array}{ll}0, & t \leq 0 \\ 1, & t>0\end{array}\right.$.

Definition 2.2. [8] A mapping $t:[0,1] \times[0,1] \rightarrow[0,1]$ is called a $t$-norm if it satisfies the following conditions :

$$
\begin{align*}
& \mathrm{t}(\mathrm{a}, 1)=\mathrm{a},  \tag{t-1}\\
& \mathrm{t}(\mathrm{a}, \mathrm{~b})=\mathrm{t}(0,0)=0  \tag{t-2}\\
& \mathrm{t}(\mathrm{c}, \mathrm{~d}, \mathrm{~d}) \geq \mathrm{t}(\mathrm{a}, \mathrm{~b}) ;  \tag{t-3}\\
& \mathrm{t}(\mathrm{t}(\mathrm{a}, \mathrm{~b}), \mathrm{c})=\mathrm{t}(\mathrm{a}, \mathrm{t}(\mathrm{~b}, \mathrm{c})) \text { for all } \mathrm{a}, \mathrm{~b}, \mathrm{c}, \mathrm{~d} \in[0,1] \tag{t-4}
\end{align*}
$$

Definition 2.3. [8] A probabilistic metric space (PM-space) is an ordered pair (X,F) consisting of a non-empty set X and a function $F: \mathrm{X} \times \mathrm{X} \rightarrow \mathrm{L}$, where L is the collection of all distribution functions and the value of $F$ at $(u, v) \in X \times X$ is represented by $F_{u, v}$. The function $F_{u, v}$ assumed to satisfy the following conditions:
(PM-1 ) $\mathrm{F}_{\mathrm{u}, \mathrm{v}}(\mathrm{x})=1$, for all $\mathrm{x}>0$, if and only if $\mathrm{u}=\mathrm{v}$;
$(\mathrm{PM}-2) \mathrm{F}_{\mathrm{u}, \mathrm{v}}(0)=0$;
(PM-3) $\mathrm{F}_{\mathrm{u}, \mathrm{v}}=\mathrm{F}_{\mathrm{v}, \mathrm{u}}$;
(PM-4) If $\mathrm{F}_{\mathrm{u}, \mathrm{v}}(\mathrm{x})=1$ and $\mathrm{F}_{\mathrm{v}, \mathrm{w}}(\mathrm{y})=1$ then $\mathrm{F}_{\mathrm{u}, \mathrm{w}}(\mathrm{x}+\mathrm{y})=1$, for all $\mathrm{u}, \mathrm{v}, \mathrm{w} \in \mathrm{X}$ and $\mathrm{x}, \mathrm{y}>0$.
Definition 2.4. [8] A Menger space is a triplet ( $\mathrm{X}, \mathcal{F}, \mathrm{t}$ ) where ( $\mathrm{X}, \mathcal{F}$ ) is a PM-space and t is a t -norm such that the inequality
$(P M-5) F_{u, w}(x+y) \geq t\left\{F_{u, v}(x), F_{v, w}(y)\right\}$, for all $u, v, w \in X, x, y \geq 0$.
Definition 2.5. [8] A sequence $\left\{\mathrm{x}_{\mathrm{n}}\right\}$ in a Menger space ( $\mathrm{X}, \boldsymbol{F}, \mathrm{t}$ ) is said to be convergent and converges to a point X in X if and only if for each $\varepsilon>0$ and $\lambda>0$, there is an integer $\mathrm{M}(\varepsilon, \lambda)$ such that

$$
\mathrm{F}_{\mathrm{x}_{\mathrm{n}}, \mathrm{x}}(\varepsilon)>1-\lambda \text { for all } \mathrm{n} \geq \mathrm{M}(\varepsilon, \lambda)
$$

Further the sequence $\left\{\mathrm{x}_{\mathrm{n}}\right\}$ is said to be Cauchy sequence if for $\varepsilon>0$ and $\lambda>0$, there is an integer $M(\varepsilon, \lambda)$ such that

$$
\mathrm{F}_{\mathrm{x}_{\mathrm{n},} \mathrm{x}_{\mathrm{m}}}(\varepsilon)>1-\lambda \quad \text { for all } \mathrm{m}, \mathrm{n} \geq \mathrm{M}(\varepsilon, \lambda)
$$

A Menger PM-space ( $\mathrm{X}, \mathrm{F}, \mathrm{t}$ ) is said to be complete if every Cauchy sequence in X converges to a point in X .

A complete metric space can be treated as a complete Menger space in the following way:
Proposition 2.1. [8] If ( $\mathrm{X}, \mathrm{d}$ ) is a metric space then the metric d induces mappings $\boldsymbol{F}: \mathrm{X} \times \mathrm{X} \rightarrow \mathrm{L}$, defined by $\mathrm{F}_{\mathrm{p}, \mathrm{q}}(\mathrm{x})=\mathrm{H}(\mathrm{x}-\mathrm{d}(\mathrm{p}, \mathrm{q})), \mathrm{p}, \mathrm{q} \in \mathrm{X}$, where

$$
H(k)=0, \quad \text { for } k \leq 0 \text { and } H(k)=1, \quad \text { for } k>0 .
$$

Further if, $t:[0,1] \times[0,1] \rightarrow[0,1]$ is defined by $t(a, b)=\min \{a, b\}$. Then $(X, F, t)$ is a Menger space. It is complete if $(X, d)$ is complete.

The space ( $\mathrm{X}, \mathrm{F}, \mathrm{t}$ ) so obtained is called the induced Menger space.
Definition 2.6. [1] Self mappings $A$ and $S$ of a Menger space ( $X, F, t$ ) are said to be weak compatible if they commute at their coincidence points i.e. $A x=S x$ for $x \in X$ implies $A S x=S A x$.

Definition 2.7. [1] Self mappings $A$ and $S$ of a Menger space (X, $\mathcal{F}, \mathrm{t}$ ) are said to be compatible if $\mathrm{F}_{\mathrm{ASx}_{\mathrm{n}}, S A x_{n}}(\mathrm{x}) \rightarrow 1$ for all $\mathrm{x}>0$, whenever $\left\{\mathrm{x}_{\mathrm{n}}\right\}$ is a sequence in X such that $\mathrm{Ax}_{\mathrm{n}}, S \mathrm{~S}_{\mathrm{n}} \rightarrow \mathrm{u}$ for some u in X , as $\mathrm{n} \rightarrow \infty$.
Definition 2.8. [12] Self maps A and $S$ of a Menger PM-space (X, $\boldsymbol{F}, \mathrm{t}$ ) are said to be occasionally weakly compatible (owc) if and only if there is a point $x$ in $X$ which is coincidence point of $A$ and $S$ at which $A$ and $S$ commute.
Example 2.1. Let $(X, F, t)$ be the Menger PM-space, where $X=[0,4]$. Define F by

$$
F_{x, y}(t)= \begin{cases}\frac{t}{t+|x-y|}, & \text { if } t>0 \\ 0, & \text { if } t=0\end{cases}
$$

Define A, S: X $\rightarrow \mathrm{X}$ by
$A x=9 x$ and $S x=x^{3}$ for all $x \in X$ then $A x=S x$ for $x=0$ and 3 .
But $\operatorname{AS}(0)=S A(0)$ and $\operatorname{AS}(9) \neq \operatorname{SA}(9)$.
Thus, S and T are occasionally weakly compatible mappings but not weakly compatible.
Remark 2.1. In view of above example, it follows that the concept of occasionally weakly compatible is more general than that of weak compatibility.
Lemma 2.1. [1] Let $(X, F, *)$ be a Menger space with $t$-norm $*$ such that the family $\left\{{ }_{\mathrm{n}}^{*}(\mathrm{x})\right\}_{\mathrm{n} \in \mathrm{N}}$ is equicontinuous at $x=1$ and let $E$ denote the family of all functions $\phi: \mathrm{R}^{+} \rightarrow \mathrm{R}^{+}$such that $\phi$ is nondecreasing with $\lim _{\mathrm{n} \rightarrow \infty} \phi^{\mathrm{n}}(\mathrm{t})=+\infty, \forall \mathrm{t}>0$. If $\left\{\mathrm{y}_{\mathrm{n}}\right\}_{\mathrm{n} \in \mathrm{N}}$ is a sequence in X satisfying the condition

$$
\mathrm{F}_{\mathrm{y}_{\mathrm{n}}, \mathrm{y}_{\mathrm{n}+1}}(\mathrm{t}) \quad \geq \mathrm{F}_{\mathrm{y}_{\mathrm{n}-1}, \mathrm{y}_{\mathrm{n}}}(\phi(\mathrm{t}))
$$

for all $\mathrm{t}>0$ and $\alpha \in[-1,0]$, then $\left\{\mathrm{y}_{\mathrm{n}}\right\}_{\mathrm{n} \in \mathrm{N}}$ is a Cauchy sequence in X .
Proposition 2.2. Let $\left\{x_{n}\right\}$ be a Cauchy sequence in a Menger space $(X, \mathcal{F}, t)$ with continuous $t$-norm $t$. If the subsequence $\left\{x_{2 n}\right\}$ converges to $x$ in $X$, then $\left\{x_{n}\right\}$ also converges to $x$.
Proof. As $\left\{x_{2 n}\right\}$ converges to $x$, we have

$$
F_{x_{n}, x}(\varepsilon) \geq t\left(F_{x_{n}, x_{2 n}}\left(\frac{\varepsilon}{2}\right), F_{x_{2 n}, x}\left(\frac{\varepsilon}{2}\right)\right)
$$

Then

$$
\lim _{n \rightarrow \infty} F_{x_{n}, x}(\varepsilon) \geq t(1,1) \text {, which gives } \lim _{n \rightarrow \infty} F_{x_{n}, x}(\varepsilon)=1, \forall \varepsilon>0 \text { and the result follows. }
$$

## 3. Main Result

Theorem 3.1. Let A, B, S, T, P and Q be self mappings on a Menger space ( $\mathrm{X}, \boldsymbol{F}, \boldsymbol{*}^{*}$ ) with continuous t-norm * satisfying :
(3.1.1) $\mathrm{P}(\mathrm{X}) \subseteq \mathrm{ST}(\mathrm{X}), \mathrm{Q}(\mathrm{X}) \subseteq \mathrm{AB}(\mathrm{X}) ;$
(3.1.2) $\mathrm{AB}=\mathrm{BA}, \quad \mathrm{ST}=\mathrm{TS}, \mathrm{PB}=\mathrm{BP}, \quad \mathrm{QT}=\mathrm{TQ}$;
(3.1.3) One of $\mathrm{ST}(\mathrm{X}), \mathrm{Q}(\mathrm{X}), \mathrm{AB}(\mathrm{X})$ or $\mathrm{P}(\mathrm{X})$ is complete;
(3.1.4) The pairs $(\mathrm{P}, \mathrm{AB})$ and $(\mathrm{Q}, \mathrm{ST})$ are occasionally weak compatible;
(3.1.5) $\left[1+\alpha \mathrm{F}_{\text {ABx, STy }}(\mathrm{t})\right] * \mathrm{~F}_{\mathrm{Px}, \mathrm{Qy}}(\mathrm{t})$

$$
\begin{aligned}
\geq & \alpha \min \left\{\mathrm{F}_{\mathrm{Px}, \mathrm{ABx}}(\mathrm{t}) * \mathrm{~F}_{\mathrm{Qy}, \mathrm{STy}}(\mathrm{t}), \mathrm{F}_{\mathrm{Px}, \mathrm{STy}}(2 \mathrm{t}) * \quad \mathrm{~F}_{\mathrm{Qy}, \mathrm{ABx}}(2 \mathrm{t})\right\} \\
& +\mathrm{F}_{\mathrm{ABx}, \mathrm{STy}}(\phi(\mathrm{t})) * \mathrm{~F}_{\mathrm{Px}, \mathrm{ABx}}(\phi(\mathrm{t})) * \mathrm{~F}_{\mathrm{Qy}, \mathrm{STy}}(\phi(\mathrm{t})) * \mathrm{~F}_{\mathrm{Px}, \mathrm{STy}}(2 \phi(\mathrm{t})) * \mathrm{~F}_{\mathrm{Qy}, \mathrm{ABx}}(2 \phi(\mathrm{t}))
\end{aligned}
$$

for all $\mathrm{x}, \mathrm{y} \in \mathrm{X}, \mathrm{t}>0$ and $\phi \in \mathrm{E}$.
Then $\mathrm{A}, \mathrm{B}, \mathrm{S}, \mathrm{T}, \mathrm{P}$ and Q have a unique common fixed point in X .
Proof. Suppose $x_{0} \in X$. From condition (3.1.1) $\exists x_{1}, x_{2} \in X$ such that

$$
\mathrm{Px}_{0}=\mathrm{STx}_{1} \text { and } \mathrm{Qx}_{1}=\mathrm{ABx}_{2}
$$

Inductively, we can construct sequences $\left\{x_{n}\right\}$ and $\left\{y_{n}\right\}$ in $X$ such that

$$
\mathrm{y}_{2 \mathrm{n}}=\mathrm{Px}_{2 \mathrm{n}}=\operatorname{STx}_{2 \mathrm{n}+1} \quad \text { and } \quad \mathrm{y}_{2 \mathrm{n}+1}=\mathrm{Qx}_{2 \mathrm{n}+1}=\mathrm{ABx}_{2 \mathrm{n}+2} \quad \text { for } \mathrm{n}=0,1,2, \ldots
$$

Step I. Let us show that $\mathrm{F}_{\mathrm{y}_{\mathrm{n}+2}, \mathrm{y}_{\mathrm{n}+1}}(\mathrm{t}) \geq \mathrm{F}_{\mathrm{y}_{\mathrm{n}+1}, \mathrm{y}_{\mathrm{n}}}(\phi(\mathrm{t}))$.
For, putting $\mathrm{x}_{2 \mathrm{n}+2}$ for x and $\mathrm{x}_{2 \mathrm{n}+1}$ for y in (3.1.5) and then on simplification, we have

$$
\begin{align*}
& {\left[1+\alpha \mathrm{F}_{\mathrm{ABx}_{2 \mathrm{n}+2},}, \mathrm{STx}_{2 \mathrm{n}+1}(\mathrm{t})\right] * \mathrm{~F}_{\mathrm{Px}_{2 \mathrm{n}+2}, \mathrm{Qx}_{2 \mathrm{n}+1}}(\mathrm{t})} \\
& \geq \alpha \min \left\{\mathrm{F}_{\mathrm{Px}_{2 \mathrm{n}+2}, \mathrm{ABx}_{2 \mathrm{n}+2}}(\mathrm{t}){ }^{*} \mathrm{~F}_{\mathrm{Qx}_{2 \mathrm{n}+1}, \mathrm{STx}_{2 \mathrm{n}+1}}(\mathrm{t}), \mathrm{F}_{\mathrm{Px}_{2 \mathrm{n}+2}, \mathrm{STx}_{2 \mathrm{n}+1}}(2 \mathrm{t}) \mathrm{F}_{\mathrm{Qx}_{2 \mathrm{n}+1}, \mathrm{ABx}_{2 \mathrm{n}+2}}\right.  \tag{2t}\\
& +\mathrm{F}_{\mathrm{ABx}_{2 \mathrm{n}+2}, \mathrm{STx}_{2 \mathrm{n}+1}}(\phi(\mathrm{t})) * \mathrm{~F}_{\mathrm{Px}_{2 \mathrm{n}+2}, \mathrm{ABx}_{2 \mathrm{n}+2}}(\phi(\mathrm{t})) * \mathrm{~F}_{\mathrm{Qx}_{2 \mathrm{n}+1}, \mathrm{STx}_{2 \mathrm{n}+1}}(\phi(\mathrm{t})) \\
& *^{\mathrm{F}_{\mathrm{Px}_{2 \mathrm{n}+2}}, \mathrm{STx}_{2 \mathrm{n}+1}}(2 \phi(\mathrm{t})) * \mathrm{~F}_{\mathrm{Qx}_{2 \mathrm{n}+1}, A B x_{2 \mathrm{n}+2}}(2 \phi(\mathrm{t})) \\
& {\left[1+\alpha \mathrm{F}_{\mathrm{y}_{2 \mathrm{n}+1},}, \mathrm{y}_{2 \mathrm{n}}(\mathrm{t})\right] * \mathrm{~F}_{\mathrm{y}_{2 \mathrm{n}+2}}, \mathrm{y}_{2 \mathrm{n}+1}(\mathrm{t})} \\
& \geq \alpha \min \left\{\mathrm{F}_{\mathrm{y}_{2 \mathrm{n}+2}, \mathrm{y}_{2 \mathrm{n}+1}}(\mathrm{t}) * \mathrm{~F}_{\mathrm{y}_{2 \mathrm{n}+1}, \mathrm{y}_{2 \mathrm{n}}}(\mathrm{t}), \mathrm{F}_{\mathrm{y}_{2 \mathrm{n}+2}, \mathrm{y}_{2 \mathrm{n}}}(2 \mathrm{t}) * \mathrm{~F}_{\mathrm{y}_{2 \mathrm{n}+1}, \mathrm{y}_{2 \mathrm{n}+1}}(2 \mathrm{t})\right\}+\mathrm{F}_{\mathrm{y}_{2 \mathrm{n}+1}, \mathrm{y}_{2 \mathrm{n}}} \\
& * \mathrm{~F}_{\mathrm{y}_{2 \mathrm{n}+2}, \mathrm{y}_{2 \mathrm{n}+1}}(\phi(\mathrm{t})) * \mathrm{~F}_{\mathrm{y}_{2 \mathrm{n}+1}, \mathrm{y}_{2 \mathrm{n}}}(\phi(\mathrm{t})) * \mathrm{~F}_{\mathrm{y}_{2 \mathrm{n}+2}, \mathrm{y}_{2 \mathrm{n}}}(2 \phi(\mathrm{t})) * \mathrm{~F}_{\mathrm{y}_{2 \mathrm{n}+1}, \mathrm{y}_{2 \mathrm{n}+1}}(2 \phi(\mathrm{t})) \\
& \mathrm{F}_{\mathrm{y}_{2 \mathrm{n}+2}, \mathrm{y}_{2 \mathrm{n}+1}}(\mathrm{t})+\alpha \mathrm{F}_{\mathrm{y}_{2 \mathrm{n}+1}, \mathrm{y}_{2 \mathrm{n}}}(\mathrm{t}) * \mathrm{~F}_{\mathrm{y}_{2 \mathrm{n}+2}, \mathrm{y}_{2 \mathrm{n}+1}}(\mathrm{t}) \\
& \geq \alpha \min \left\{\mathrm{F}_{\mathrm{y}_{2 \mathrm{n}+2}, \mathrm{y}_{2 \mathrm{n}}}(2 \mathrm{t}), \mathrm{F}_{\mathrm{y}_{2 \mathrm{n}+2}, \mathrm{y}_{2 \mathrm{n}}}(2 \mathrm{t})\right\}+\mathrm{F}_{\mathrm{y}_{2 \mathrm{n}+1}, \mathrm{y}_{2 \mathrm{n}}}(\phi(\mathrm{t})) * \mathrm{~F}_{\mathrm{y}_{2 \mathrm{n}+2}, \mathrm{y}_{2 \mathrm{n}+1}}(\phi(\mathrm{t})) \\
& *_{\mathrm{y}_{2 \mathrm{n}+2}, \mathrm{y}_{2 \mathrm{n}}}(2 \phi(\mathrm{t})){ }^{*} 1 \\
& \mathrm{~F}_{\mathrm{y}_{2 \mathrm{n}+2}, \mathrm{y}_{2 \mathrm{n}+1}}(\mathrm{t})+\alpha \mathrm{F}_{\mathrm{y}_{2 \mathrm{n}+1}, \mathrm{y}_{2 \mathrm{n}}}(\mathrm{t}) * \mathrm{~F}_{\mathrm{y}_{2 \mathrm{n}+2}, \mathrm{y}_{2 \mathrm{n}+1}}(\mathrm{t}) \\
& \geq \alpha \mathrm{F}_{\mathrm{y}_{2 \mathrm{n}+2}, \mathrm{y}_{2 \mathrm{n}}}(2 \mathrm{t})+\mathrm{F}_{\mathrm{y}_{2 \mathrm{n}+1}, \mathrm{y}_{2 \mathrm{n}}}(\phi(\mathrm{t})) * \mathrm{~F}_{\mathrm{y}_{2 \mathrm{n}+2}, \mathrm{y}_{2 \mathrm{n}+1}}(2 \phi(\mathrm{t})) \\
& \mathrm{F}_{\mathrm{y}_{2 \mathrm{n}+2}, \mathrm{y}_{2 \mathrm{n}+1}}(\mathrm{t})+\alpha \mathrm{F}_{\mathrm{y}_{2 \mathrm{n}+2}, \mathrm{y}_{2 \mathrm{n}}}(2 \mathrm{t}) \\
& \geq \alpha \mathrm{F}_{\mathrm{y}_{2 \mathrm{n}+2}, \mathrm{y}_{2 \mathrm{n}}}(2 \mathrm{t})+\mathrm{F}_{\mathrm{y}_{2 \mathrm{n}+1}, \mathrm{y} 2 \mathrm{n}}(\phi(\mathrm{t})) * \mathrm{~F}_{\mathrm{y}_{2 \mathrm{n}+2}, \mathrm{y}_{2 \mathrm{n}+1}}(\phi(\mathrm{t})) * \mathrm{~F}_{\mathrm{y}_{2 \mathrm{n}+1}, \mathrm{y}_{2 \mathrm{n}}}(\phi(\mathrm{t})) \\
& \mathrm{F}_{\mathrm{y}_{2 \mathrm{n}+2}, \mathrm{y}_{2 \mathrm{n}+1}}(\mathrm{t}) \geq \mathrm{F}_{\mathrm{y}_{2 \mathrm{n}+1}, \mathrm{y}_{2 \mathrm{n}}}(\phi(\mathrm{t})) * \mathrm{~F}_{\mathrm{y}_{2 \mathrm{n}+2}, \mathrm{y}_{2 \mathrm{n}+1}}(\phi(\mathrm{t})) \\
& \text { or, } \mathrm{F}_{\mathrm{y}_{2 \mathrm{n}+2}, \mathrm{y}_{2 \mathrm{n}+1}}(\mathrm{t}) \geq \mathrm{F}_{\mathrm{y}_{2 \mathrm{n}+1}, \mathrm{y}_{2 \mathrm{n}+2}}(\phi(\mathrm{t})) * \mathrm{~F}_{\mathrm{y}_{2 \mathrm{n}}, \mathrm{y}_{2 \mathrm{n}+1}}(\phi(\mathrm{t})) \\
& \text { or, } \mathrm{F}_{\mathrm{y}_{2 \mathrm{n}+2}, \mathrm{y}_{2 \mathrm{n}+1}}(\mathrm{t}) \geq \min \left\{\mathrm{F}_{\mathrm{y}_{2 \mathrm{n}+1}, \mathrm{y}_{2 \mathrm{n}+2}}(\phi(\mathrm{t})), \mathrm{F}_{\mathrm{y}_{2 \mathrm{n}}, \mathrm{y}_{2 \mathrm{n}+1}}(\phi(\mathrm{t}))\right\} \text {. } \\
& \text { If } \mathrm{F}_{\mathrm{y}_{2 \mathrm{n}+1}, \mathrm{y}_{2 \mathrm{n}+2}}(\phi(\mathrm{t})) \text { is chosen 'min' then we obtain } \\
& \mathrm{F}_{\mathrm{y}_{2 \mathrm{n}+2}, \mathrm{y}_{2 \mathrm{n}+1}}(\mathrm{t}) \geq \mathrm{F}_{\mathrm{y}_{2 \mathrm{n}+2}, \mathrm{y}_{2 \mathrm{n}+1}}(\phi(\mathrm{t})), \quad \forall \mathrm{t}>0
\end{align*}
$$

a contradiction as $\phi(\mathrm{t})$ is non-decreasing function.

Thus,

$$
\mathrm{F}_{\mathrm{y}_{2 \mathrm{n}+2}, \mathrm{y}_{2 \mathrm{n}+1}}(\mathrm{t}) \geq \mathrm{F}_{\mathrm{y}_{2 \mathrm{n}+1}, \mathrm{y}_{2 \mathrm{n}}}(\phi(\mathrm{t})), \quad \forall \mathrm{t}>0 .
$$

Similarly, by putting $\mathrm{x}_{2 \mathrm{n}+2}$ for x and $\mathrm{x}_{2 \mathrm{n}+3}$ for y in (3.1.5), we have

$$
\mathrm{F}_{\mathrm{y}_{2 \mathrm{n}+3}, \mathrm{y}_{2 \mathrm{n}+2}}(\mathrm{t}) \geq \mathrm{F}_{\mathrm{y}_{2 \mathrm{n}+2}, \mathrm{y}_{2 \mathrm{n}+1}}(\phi(\mathrm{t})), \quad \forall \mathrm{t}>0 .
$$

Using these two, we obtain

$$
\mathrm{F}_{\mathrm{y}_{\mathrm{n}+2}, \mathrm{y}_{\mathrm{n}+1}}(\mathrm{t}) \geq \mathrm{F}_{\mathrm{y}_{\mathrm{n}+1}, \mathrm{y}_{\mathrm{n}}}(\phi(\mathrm{t})), \quad \forall \mathrm{n}=0,1,2, \ldots, \mathrm{t}>0
$$

Therefore, by lemma 2.1, $\left\{y_{n}\right\}$ is a Cauchy sequence in $X$.
Case I. $\mathbf{S T}(\mathbf{X})$ is complete. In this case $\left\{\mathrm{y}_{2 n}\right\}=\left\{\mathrm{STx}_{2 n+1}\right\}$ is a Cauchy sequence in $\mathrm{ST}(\mathrm{X})$, which is complete. Thus $\left\{\mathrm{y}_{2 \mathrm{n}+1}\right\}$ converges to some $\mathrm{z} \in \mathrm{ST}(\mathrm{X})$. By proposition 2.2 , we have

$$
\begin{align*}
& \left\{\mathrm{Qx}_{2 \mathrm{n}+1}\right\} \rightarrow \mathrm{z} \quad \text { and } \quad\left\{\mathrm{STx}_{2 \mathrm{n}+1}\right\} \rightarrow \mathrm{z},  \tag{3.1.6}\\
& \left\{\mathrm{Px}_{2 \mathrm{n}}\right\} \rightarrow \mathrm{z} \quad \text { and } \quad\left\{\mathrm{ABx}_{2 \mathrm{n}}\right\} \rightarrow \mathrm{z} . \tag{3.1.7}
\end{align*}
$$

As $z \in S T(X)$ there exists $u \in X$ such that $z=S T u$.
Step I. Put $\mathrm{x}=\mathrm{x}_{2 \mathrm{n}}$ and $\mathrm{y}=\mathrm{u}$ in (3.1.5), we get

$$
\begin{aligned}
& {\left[1+\alpha \mathrm{F}_{\mathrm{ABx}_{2 \mathrm{n}}, \mathrm{STu}}(\mathrm{t})\right]{ }^{*} \mathrm{~F}_{\mathrm{Px}_{2 \mathrm{n}}, \mathrm{Qu}}{ }^{(\mathrm{t})}} \\
& \geq \alpha \min \left\{\mathrm{F}_{\mathrm{Px}_{2 \mathrm{n}}, \mathrm{ABx}}^{2 \mathrm{n}}{ }^{(\mathrm{t})}{ }^{*} \mathrm{~F}_{\mathrm{Qu}, \mathrm{STu}}(\mathrm{t}), \mathrm{F}_{\mathrm{Px}_{2 \mathrm{n}}, \mathrm{STu}}(2 \mathrm{t}) * \mathrm{~F}_{\mathrm{Qu}_{\mathrm{ABx}}^{2 n}}(2 \mathrm{t})\right\} \\
& \left.+\mathrm{F}_{\mathrm{ABx}_{2 \mathrm{n}, \mathrm{STu}}}(\phi(\mathrm{t})) * \mathrm{~F}_{\mathrm{Px}_{2 \mathrm{n}}, \mathrm{ABx}}^{2 \mathrm{n}} \mathrm{C}(\mathrm{t})\right) * \mathrm{~F}_{\mathrm{Qu}, \mathrm{STu}}(\phi(\mathrm{t})) * \mathrm{~F}_{\mathrm{Px}_{2 \mathrm{n}}, \mathrm{STu}}(2 \phi(\mathrm{t})) \\
& *^{\mathrm{F}_{\mathrm{Qu}, A B x_{2 n}}} \text { (2申(t)). }
\end{aligned}
$$

Letting $\mathrm{n} \rightarrow \infty$ and using (3.1.6), (3.1.7), we get

$$
\begin{aligned}
& {\left[1+\alpha \mathrm{F}_{z, z}(\mathrm{t})\right] * \mathrm{~F}_{\mathrm{z}, \mathrm{Qu}}(\mathrm{t})} \\
& \geq \alpha \min \left\{\mathrm{F}_{z, z}(\mathrm{t}) * \mathrm{~F}_{\mathrm{Qu}, \mathrm{z}}(\mathrm{t}), \mathrm{F}_{\mathrm{z}, \mathrm{z}}(2 \mathrm{t}) * \mathrm{~F}_{\mathrm{Qu}, \mathrm{z}}(2 \mathrm{t})\right\} \\
& +\mathrm{F}_{z, z}(\phi(\mathrm{t})){ }^{*} \mathrm{~F}_{\mathrm{z}, \mathrm{z}}(\phi(\mathrm{t})) \\
& \text { * } \mathrm{F}_{\mathrm{Qu}, z}(\phi(\mathrm{t})) * \mathrm{~F}_{z, z}(2 \phi(\mathrm{t})) * \mathrm{~F}_{\mathrm{Qu}, \mathrm{z}}(2 \phi(\mathrm{t})) \\
& \mathrm{F}_{z, \mathrm{Qu}}(\mathrm{t})+\alpha \mathrm{F}_{z, \mathrm{Qu}}(\mathrm{t}) \geq \alpha \min \left\{\mathrm{F}_{\mathrm{Qu}, z}(\mathrm{t}), \mathrm{F}_{\mathrm{Qu}, z}(2 \mathrm{t})\right\}+\mathrm{F}_{\mathrm{Qu}, z}(\phi(\mathrm{t})) * \mathrm{~F}_{\mathrm{Qu}, z}(2 \phi(\mathrm{t})) \\
& \mathrm{F}_{\mathrm{Qu}, z}(\mathrm{t})+\alpha \mathrm{F}_{\mathrm{Qu}, z}(\mathrm{t}) \geq \alpha \min \left\{\mathrm{F}_{\mathrm{Qu}, z}(\mathrm{t}), \mathrm{F}_{\mathrm{Qu}, z}(\mathrm{t}) * \mathrm{~F}_{z, z}(\mathrm{t})\right\}+\mathrm{F}_{\mathrm{Qu}, z}(\phi(\mathrm{t})) * \mathrm{~F}_{\mathrm{Qu}, z}(\phi(\mathrm{t})) * \mathrm{~F}_{z, z}(\phi(\mathrm{t})) \\
& \mathrm{F}_{\mathrm{Qu}, z}(\mathrm{t})+\alpha \mathrm{F}_{\mathrm{Qu}, z}(\mathrm{t}) \geq \alpha \mathrm{F}_{\mathrm{Qu}, z}(\mathrm{t})+\mathrm{F}_{\mathrm{Qu}, z}(\phi(\mathrm{t})) \\
& \mathrm{F}_{\mathrm{Qu}, \mathrm{z}}(\mathrm{t}) \geq \mathrm{F}_{\mathrm{Qu}, \mathrm{z}}(\phi(\mathrm{t}))
\end{aligned}
$$

which is a contradiction and we get

$$
\mathrm{Qu}=\mathrm{z} \text { and so } \mathrm{Qu}=\mathrm{z}=\mathrm{STu} \text {. }
$$

Since ( $\mathrm{Q}, \mathrm{ST}$ ) is occasionally weakly compatible, we have

$$
\mathrm{STz}=\mathrm{Qz} .
$$

Step III. Put $\mathrm{x}=\mathrm{x}_{2 \mathrm{n}}$ and $\mathrm{y}=\mathrm{Tz}$ in (3.1.5), we have

$$
\begin{aligned}
& {\left[1+\alpha \mathrm{F}_{\mathrm{ABx}_{2 \mathrm{n}}, \mathrm{STTz}}(\mathrm{t})\right] * \mathrm{~F}_{\mathrm{Px}_{2 \mathrm{n}}, \text { QTz }}(\mathrm{t})} \\
& \left.\geq \alpha \min \left\{\mathrm{F}_{\mathrm{Px}_{2 \mathrm{n}}, \mathrm{ABx}_{2 \mathrm{n}}}(\mathrm{t}) * \mathrm{~F}_{\mathrm{QTz}, \mathrm{STTz}}(\mathrm{t}), \mathrm{F}_{\mathrm{Px}_{2 \mathrm{n}}, \mathrm{STTz}}(2 \mathrm{t}) * \mathrm{~F}_{\mathrm{QTz}, \mathrm{ABx}}^{2 \mathrm{n}} \text { ( } 2 \mathrm{t}\right)\right\}
\end{aligned}
$$

$$
\begin{aligned}
& \text { * } \mathrm{F}_{\mathrm{Px}_{2 \mathrm{n}}, \mathrm{STTz}}(2 \phi(\mathrm{t})) \quad * \mathrm{~F}_{\mathrm{QTz}, \mathrm{ABx}}^{2 \mathrm{n}} \mathrm{n}(2 \phi(\mathrm{t})) \text {. }
\end{aligned}
$$

As $\mathrm{QT}=\mathrm{TQ}$ and $\mathrm{ST}=\mathrm{TS}$, we have

$$
\mathrm{QTz}=\mathrm{TQz}=\mathrm{Tz} \quad \text { and } \quad \mathrm{ST}(\mathrm{Tz})=\mathrm{T}(\mathrm{STz})=\mathrm{Tz} .
$$

Letting $\mathrm{n} \rightarrow \infty$, we get

$$
\begin{aligned}
& {\left[1+\alpha \mathrm{F}_{z, \mathrm{Tz}}(\mathrm{t})\right] * \mathrm{~F}_{z, \mathrm{Tz}}(\mathrm{t}) \geq \alpha \min \left\{\mathrm{F}_{\mathrm{z}, \mathrm{z}}(\mathrm{t}) * \mathrm{~F}_{\mathrm{Tz}, \mathrm{Tz}}(\mathrm{t}), \mathrm{F}_{\mathrm{z}, \mathrm{Tz}}(2 \mathrm{t}) * \mathrm{~F}_{\mathrm{T} z, \mathrm{z}}(2 \mathrm{t})\right\}} \\
& +\mathrm{F}_{z, \mathrm{~T} z}(\phi(\mathrm{t})){ }^{2} \mathrm{~F}_{\mathrm{z}, \mathrm{z}}(\phi(\mathrm{t})) \\
& \text { * } \mathrm{F}_{\mathrm{Tz}, \mathrm{Tz}}(\phi(\mathrm{t})) * \mathrm{~F}_{\mathrm{z}, \mathrm{Tz}}(2 \phi(\mathrm{t})) * \mathrm{~F}_{\mathrm{Tz}, \mathrm{z}}(2 \phi(\mathrm{t})) \\
& \mathrm{F}_{\mathrm{z}, \mathrm{Tz}}(\mathrm{t})+\alpha\left\{\mathrm{F}_{z, \mathrm{Tz}}(\mathrm{t}) * \mathrm{~F}_{\mathrm{z}, \mathrm{Tz}}(\mathrm{t})\right\} \geq \alpha \min \left\{1 * \mathrm{~F}_{\mathrm{T}, \mathrm{z}}(2 \mathrm{t})\right\}+\mathrm{F}_{z, \mathrm{Tz}}(\phi(\mathrm{t})) * 1 * 1 * \mathrm{~F}_{\mathrm{Tz}, \mathrm{z}}(2 \phi(\mathrm{t})) \\
& \mathrm{F}_{\mathrm{Tz}, z}(\mathrm{t})+\alpha \mathrm{F}_{\mathrm{Tz}, z}(\mathrm{t}) \geq \alpha \mathrm{F}_{\mathrm{Tz}, \mathrm{z}}(2 \mathrm{t})+\mathrm{F}_{\mathrm{Tz}, z}(\phi(\mathrm{t})) * \mathrm{~F}_{\mathrm{T}, \mathrm{z}}(2 \phi(\mathrm{t})) \\
& \mathrm{F}_{\mathrm{T},, z}(\mathrm{t})+\alpha \mathrm{F}_{\mathrm{T}, z, \mathrm{z}}(\mathrm{t}) \geq \alpha\left\{\mathrm{F}_{\mathrm{T} z, z}(\mathrm{t}) * \mathrm{~F}_{z, \mathrm{z}}(\mathrm{t})\right\}+\mathrm{F}_{\mathrm{T}, z, \mathrm{z}}(\phi(\mathrm{t})) * \mathrm{~F}_{\mathrm{T}, \mathrm{z}}(\phi(\mathrm{t})) * \mathrm{~F}_{\mathrm{z}, \mathrm{z}}(\phi(\mathrm{t})) \\
& \mathrm{F}_{\mathrm{Tz}, \mathrm{z}}(\mathrm{t})+\alpha \mathrm{F}_{\mathrm{Tz}, \mathrm{z}}(\mathrm{t}) \geq \alpha \mathrm{F}_{\mathrm{Tz}, \mathrm{z}}(\mathrm{t})+\mathrm{F}_{\mathrm{Tz}, \mathrm{z}}(\mathrm{t}(\mathrm{t})) \\
& \mathrm{F}_{\mathrm{T} z, z}(\mathrm{t}) \geq \mathrm{F}_{\mathrm{Tz}, \mathrm{z}}(\phi(\mathrm{t}))
\end{aligned}
$$

which is a contradiction and we get $\mathrm{Tz}=\mathrm{z}$.
Now, $\mathrm{STz}=\mathrm{Tz}=\mathrm{z}$ implies $\mathrm{Sz}=\mathrm{z}$.
Hence, $\mathrm{Sz}=\mathrm{Tz}=\mathrm{Qz}=\mathrm{z}$.
Step IV. As $\mathrm{Q}(\mathrm{X}) \subseteq \mathrm{AB}(\mathrm{X})$, there exists $w \in X$ such that

$$
\mathrm{z}=\mathrm{Qz}=\mathrm{ABw} .
$$

Put $\mathrm{x}=\mathrm{w}$ and $\mathrm{y}=\mathrm{x}_{2 \mathrm{n}+1}$ in (3.1.5), we get

$$
\begin{aligned}
& {\left[1+\alpha \mathrm{F}_{\mathrm{ABw}, \mathrm{STx}_{2 \mathrm{n}+1}}(\mathrm{t})\right]{ }^{*} \mathrm{~F}_{\mathrm{Pw}, \mathrm{Qx}}^{2 \mathrm{n}+1} \mathrm{(t)}} \\
& \geq \alpha \min \left\{\mathrm{F}_{\mathrm{Pw}, \mathrm{ABw}}(\mathrm{t}) * \mathrm{~F}_{\mathrm{Qx}_{2 \mathrm{n}+1},}, \mathrm{STx}_{2 \mathrm{n}+1}(\mathrm{t}), \mathrm{F}_{\mathrm{Pw}, \mathrm{STx}_{2 \mathrm{n}+1}}(2 \mathrm{t})\right. \\
& \text { * } \left.\mathrm{F}_{\mathrm{Qx}_{2 \mathrm{n}+1}, \mathrm{ABw}}(2 \mathrm{t})\right\}+\mathrm{F}_{\mathrm{ABw}, \mathrm{STx}}^{2 \mathrm{n}+1} \mathrm{t}(\phi(\mathrm{t})){ }^{\left(\mathrm{F}_{\mathrm{Pw}, \mathrm{ABw}}\right.}(\phi(\mathrm{t})) \\
& \left.* \mathrm{~F}_{\mathrm{Qx}_{2 \mathrm{n}+1}, \mathrm{STx}}^{2 \mathrm{n}+1} \mathrm{( }\right) \mathrm{t}(\mathrm{t}) * \mathrm{~F}_{\mathrm{Pw}, \mathrm{STx}_{2 \mathrm{n}+1}}(2 \phi(\mathrm{t})) * \mathrm{~F}_{\mathrm{Qx}_{2 \mathrm{n}+1}, \mathrm{ABw}}(2 \phi(\mathrm{t})) .
\end{aligned}
$$

Letting $\mathrm{n} \rightarrow \infty$, we get

$$
\begin{aligned}
& {\left[1+\alpha \mathrm{F}_{z, z}(\mathrm{t})\right] * \mathrm{~F}_{\mathrm{Pw}, \mathrm{z}}(\mathrm{t}) \geq \alpha \min \left\{\mathrm{F}_{\mathrm{Pw}, z}(\mathrm{t}) * \mathrm{~F}_{\mathrm{z}, \mathrm{z}}(\mathrm{t}), \mathrm{F}_{\mathrm{Pw}, \mathrm{z}}(2 \mathrm{t}) * \mathrm{~F}_{\mathrm{z}, \mathrm{z}}(2 \mathrm{t})\right\}} \\
& +\mathrm{F}_{\mathrm{z}, \mathrm{z}}(\phi(\mathrm{t})) * \mathrm{~F}_{\mathrm{Pw}, \mathrm{z}}(\phi(\mathrm{t})) \\
& \text { * } \mathrm{F}_{z, \mathrm{z}}(\phi(\mathrm{t})){ }^{*} \mathrm{~F}_{\mathrm{Pw}, \mathrm{z}}(2 \phi(\mathrm{t})){ }^{*} \mathrm{~F}_{\mathrm{z}, \mathrm{z}}(2 \phi(\mathrm{t})) \\
& \mathrm{F}_{\mathrm{Pw}, \mathrm{z}}(\mathrm{t})+\alpha \mathrm{F}_{\mathrm{PW}, z}(\mathrm{t}) \geq \alpha \min \left\{\mathrm{F}_{\mathrm{Pw}, z}(\mathrm{t}), \mathrm{F}_{\mathrm{Pw}, \mathrm{z}}(2 \mathrm{t})\right\}+\mathrm{F}_{\mathrm{PW}, \mathrm{z}}(\mathrm{t}(\mathrm{t})) * \mathrm{~F}_{\mathrm{PW}, \mathrm{z}}(2 \phi(\mathrm{t})) \\
& \mathrm{F}_{\mathrm{Pw}, z}(\mathrm{t})+\alpha \mathrm{F}_{\mathrm{Pw}, z}(\mathrm{t}) \geq \alpha \min \left\{\mathrm{F}_{\mathrm{Pw}, z}(\mathrm{t}), \mathrm{F}_{\mathrm{Pw}, z}(\mathrm{t}) * \mathrm{~F}_{\mathrm{z}, \mathrm{z}}(\mathrm{t})\right\}+\mathrm{F}_{\mathrm{Pw}, z}(\phi(\mathrm{t})) * \mathrm{~F}_{\mathrm{z}, \mathrm{z}}(\phi(\mathrm{t}))
\end{aligned}
$$

$$
\begin{aligned}
\mathrm{F}_{\mathrm{Pw}, z}(\mathrm{t})+\alpha \mathrm{F}_{\mathrm{Pw}, z}(\mathrm{t}) & \geq \alpha \min \left\{\mathrm{F}_{\mathrm{Pw}, z}(\mathrm{t}), \mathrm{F}_{\mathrm{Pw}, z}(\mathrm{t})\right\}+\mathrm{F}_{\mathrm{Pw}, z}(\phi(\mathrm{t})) \\
\mathrm{F}_{\mathrm{Pw}, z}(\mathrm{t})+\alpha \mathrm{F}_{\mathrm{Pw}, z}(\mathrm{t}) & \left.\geq \alpha \mathrm{F}_{\mathrm{Pw}, z}(\mathrm{t})\right\}+\mathrm{F}_{\mathrm{Pw}, z}(\phi(\mathrm{t})) \\
\mathrm{F}_{\mathrm{Pw}, z}(\mathrm{t}) & \geq \mathrm{F}_{\mathrm{Pw}, z}(\phi(\mathrm{t}))
\end{aligned}
$$

which is a contradiction and hence, we get $\mathrm{Pw}=\mathrm{z}$.
Hence, $\mathrm{Pz}=\mathrm{z}=\mathrm{ABz}$.
Step V. Put $\mathrm{x}=\mathrm{z}$ and $\mathrm{y}=\mathrm{x}_{2 \mathrm{n}+1}$ in (3.1.5), we have

$$
\begin{aligned}
& {\left[1+\alpha \mathrm{F}_{\mathrm{ABz}}, \mathrm{STx}_{2 \mathrm{n}+1}(\mathrm{t})\right]{ }^{*} \mathrm{~F}_{\mathrm{Pz}, \mathrm{Qx}}^{2 \mathrm{n}+1}{ }^{(\mathrm{t})}} \\
& \geq \alpha \min \left\{\mathrm{F}_{\mathrm{Pz}, \mathrm{ABz}}(\mathrm{t}) * \mathrm{~F}_{\mathrm{Qx}_{2 \mathrm{n}+1}, \mathrm{STx}_{2 \mathrm{n}+1}}(\mathrm{t}), \mathrm{F}_{\mathrm{Pz}, \mathrm{STx}_{2 \mathrm{n}+1}}(2 \mathrm{t}) * \mathrm{~F}_{\mathrm{Qx}_{2 \mathrm{n}+1}, \mathrm{ABz}}(2 \mathrm{t})\right\} \\
& +\mathrm{F}_{\mathrm{ABz}, \mathrm{STx}_{2 \mathrm{n}+1}}(\phi(\mathrm{t})) * \mathrm{~F}_{\mathrm{Pz}, \mathrm{ABz}}(\phi(\mathrm{t})) * \mathrm{~F}_{\mathrm{Qx}_{2 \mathrm{n}+1}, \mathrm{STx}_{2 \mathrm{n}+1}}(\phi(\mathrm{t})) * \mathrm{~F}_{\mathrm{Pz}^{2} \mathrm{STx}_{2 \mathrm{n}+1}}(2 \phi(\mathrm{t})) \\
& { }^{*} \mathrm{~F}_{\mathrm{Qx}}^{2 \mathrm{n}+1}, \mathrm{ABz}(2 \phi(\mathrm{t})) \text {. }
\end{aligned}
$$

Letting $\mathrm{n} \rightarrow \infty$, we get

$$
\begin{aligned}
& {\left[1+\alpha \mathrm{F}_{\mathrm{P}, \mathrm{z}}(\mathrm{t})\right] * \mathrm{~F}_{\mathrm{P}, \mathrm{z}}(\mathrm{t})} \\
& \geq \alpha \min \left\{\mathrm{F}_{\mathrm{Pz}, \mathrm{Pz}}(\mathrm{t}) * \mathrm{~F}_{\mathrm{z}, \mathrm{z}}(\mathrm{t}), \mathrm{F}_{\mathrm{Pz}, \mathrm{z}}(2 \mathrm{t}) * \mathrm{~F}_{\mathrm{z}, \mathrm{Pz}}(2 \mathrm{t})\right\}+\mathrm{F}_{\mathrm{Pz}, \mathrm{z}}(\phi(\mathrm{t})) * \mathrm{~F}_{\mathrm{Pz}, \mathrm{Pz}}(\phi(\mathrm{t})) \\
& \text { * } \mathrm{F}_{z, z}(\phi(\mathrm{t})){ }^{*} \mathrm{~F}_{\mathrm{P}, \mathrm{z}}(2 \phi(\mathrm{t})) * \mathrm{~F}_{\mathrm{z}, \mathrm{Pz}}(2 \phi(\mathrm{t})) \\
& \mathrm{F}_{\mathrm{Pz}, \mathrm{z}}(\mathrm{t})+\alpha\left\{\mathrm{F}_{\mathrm{P}, \mathrm{z}}(\mathrm{t}) * \mathrm{~F}_{\mathrm{Pz}, \mathrm{z}}(\mathrm{t})\right\} \\
& \geq \alpha \min \left\{1 * 1, \mathrm{~F}_{\mathrm{Pz}, \mathrm{z}}(2 \mathrm{t}) * \mathrm{~F}_{\mathrm{Pz}, \mathrm{z}}(2 \mathrm{t})\right\}+\mathrm{F}_{\mathrm{Pz}, \mathrm{z}}(\phi(\mathrm{t})) * 1 * 1 * \mathrm{~F}_{\mathrm{P}, \mathrm{z}}(2 \phi(\mathrm{t})) * \mathrm{~F}_{\mathrm{z}, \mathrm{Pz}}(2 \phi(\mathrm{t})) \\
& \mathrm{F}_{\mathrm{Pz}, \mathrm{z}}(\mathrm{t})+\alpha \mathrm{F}_{\mathrm{P}, z, z}(\mathrm{t}) \geq \alpha \min \left\{1, \mathrm{~F}_{\mathrm{P}, z}(2 \mathrm{t})\right\}+\mathrm{F}_{\mathrm{P}, z, z}(\phi(\mathrm{t})) * \mathrm{~F}_{\mathrm{P}, \mathrm{z}}(2 \phi(\mathrm{t})) \\
& \mathrm{F}_{\mathrm{Pz}, \mathrm{z}}(\mathrm{t})+\alpha \mathrm{F}_{\mathrm{P}, z, z}(\mathrm{t}) \geq \alpha \mathrm{F}_{\mathrm{P}, z}(2 \mathrm{t})+\mathrm{F}_{\mathrm{Pz}, z}(\phi(\mathrm{t})) * \mathrm{~F}_{\mathrm{P}, \mathrm{z}}(2 \phi(\mathrm{t})) \\
& \mathrm{F}_{\mathrm{Pz}, \mathrm{z}}(\mathrm{t})+\alpha \mathrm{F}_{\mathrm{Pz}, \mathrm{z}}(\mathrm{t}) \geq \alpha\left\{\mathrm{F}_{\mathrm{Pz}, z}(\mathrm{t}) * \mathrm{~F}_{z, z}(\mathrm{t})\right\}+\mathrm{F}_{\mathrm{P}, z}(\phi(\mathrm{t})) * \mathrm{~F}_{\mathrm{Pz}, \mathrm{z}}(\phi(\mathrm{t})) * \mathrm{~F}_{z, z}(\phi(\mathrm{t})) \\
& \mathrm{F}_{\mathrm{P}, \mathrm{z}}(\mathrm{t})+\alpha \mathrm{F}_{\mathrm{Pz}, \mathrm{z}}(\mathrm{t}) \geq \alpha\left\{\mathrm{F}_{\mathrm{Pz}, z}(\mathrm{t}) * 1\right\}+\mathrm{F}_{\mathrm{Pz}, \mathrm{z}}(\mathrm{t}(\mathrm{t})) * 1 \\
& \mathrm{~F}_{\mathrm{Pz}, z}(\mathrm{t})+\alpha \mathrm{F}_{\mathrm{Pz}, z}(\mathrm{t}) \geq \alpha \mathrm{F}_{\mathrm{Pz}, \mathrm{z}}(\mathrm{t})+\mathrm{F}_{\mathrm{Pz}, \mathrm{z}}(\phi(\mathrm{t})) \\
& \mathrm{F}_{\mathrm{P}, \mathrm{z}, \mathrm{z}}(\mathrm{t}) \geq \mathrm{F}_{\mathrm{Pz}, \mathrm{z}}(\phi(\mathrm{t}))
\end{aligned}
$$

which is a contradiction and hence, $\mathrm{Pz}=\mathrm{z}$
and so $\mathrm{z}=\mathrm{Pz}=\mathrm{ABz}$.
Step VI. Put $\mathrm{x}=\mathrm{Bz}$ and $\mathrm{y}=\mathrm{x}_{2 \mathrm{n}+1}$ in (3.1.5), we get

$$
\begin{aligned}
& {\left[1+\alpha \mathrm{F}_{\mathrm{ABBz}, \mathrm{STx}_{2 \mathrm{n}+1}}(\mathrm{t})\right]{ }^{*} \mathrm{~F}_{\mathrm{PBz}, \mathrm{Qx}_{2 \mathrm{n}+1}}(\mathrm{t})} \\
& \geq \alpha \min \left\{\mathrm{F}_{\mathrm{PBz}, \mathrm{ABBz}}(\mathrm{t}) * \mathrm{~F}_{\mathrm{Qx}_{2 \mathrm{n}+1}, \mathrm{STx}_{2 \mathrm{n}+1}}(\mathrm{t}), \mathrm{F}_{\mathrm{PBz}, \mathrm{STx}_{2 \mathrm{n}+1}}(2 \mathrm{t})\right. \\
& \text { * } \left.\mathrm{F}_{\mathrm{Qx}}^{2 \mathrm{n}+1} \mathrm{n}, \mathrm{ABBz}(2 \mathrm{t})\right\}+\mathrm{F}_{\mathrm{ABBz}, \mathrm{STx}_{2 \mathrm{n}+1}}(\phi(\mathrm{t})){ }^{*} \mathrm{~F}_{\mathrm{PBz}, \mathrm{ABBz}}(\phi(\mathrm{t})) \\
& \text { * } \mathrm{F}_{\mathrm{Qx} 2 \mathrm{n}+1}, \mathrm{STx}_{2 \mathrm{n}+1}(\phi(\mathrm{t})){ }^{*} \mathrm{~F}_{\mathrm{PBz}, \mathrm{STx}}^{2 \mathrm{n}+1} \mathrm{(t)}(2 \phi(\mathrm{t})) * \mathrm{~F}_{\mathrm{Qx}_{2 \mathrm{n}+1}, \mathrm{ABBz}}(2 \phi(\mathrm{t})) \text {. }
\end{aligned}
$$

As $\mathrm{BP}=\mathrm{PB}, \mathrm{AB}=\mathrm{BA}$ so we have

$$
\mathrm{P}(\mathrm{Bz})=\mathrm{B}(\mathrm{Pz})=\mathrm{Bz} \text { and } \mathrm{AB}(\mathrm{Bz})=\mathrm{B}(\mathrm{AB}) \mathrm{z}=\mathrm{Bz} \text {. }
$$

Letting $n \rightarrow \infty$ and using (3.1.6), we get

$$
\begin{aligned}
& {\left[1+\alpha \mathrm{F}_{\mathrm{Bz}, \mathrm{z}}(\mathrm{t})\right] * \mathrm{~F}_{\mathrm{Bz}, \mathrm{z}}(\mathrm{t})} \\
& \geq \alpha \min \left\{\mathrm{F}_{\mathrm{Bz}, \mathrm{Bz}}(\mathrm{t}) * \mathrm{~F}_{\mathrm{z}, \mathrm{z}}(\mathrm{t}), \mathrm{F}_{\mathrm{Bz}, \mathrm{z}}(2 \mathrm{t}) * \mathrm{~F}_{\mathrm{z}, \mathrm{Bz}}(2 \mathrm{t})\right\} \\
& +\mathrm{F}_{\mathrm{Bz}, \mathrm{z}}(\phi(\mathrm{t})) * \mathrm{~F}_{\mathrm{Bz}, \mathrm{Bz}}(\phi(\mathrm{t})) * \mathrm{~F}_{\mathrm{z}, \mathrm{z}}(\phi(\mathrm{t})) * \mathrm{~F}_{\mathrm{Bz}, \mathrm{z}}(2 \phi(\mathrm{t})) * \mathrm{~F}_{\mathrm{z}, \mathrm{Bz}}(2 \phi(\mathrm{t})) \\
& \mathrm{F}_{\mathrm{Bz}, \mathrm{z}}(\mathrm{t})+\alpha\left\{\mathrm{F}_{\mathrm{Bz}, \mathrm{z}}(\mathrm{t}) * \mathrm{~F}_{\mathrm{Bz}, \mathrm{z}}(\mathrm{t})\right\} \\
& \geq \alpha \min \left\{1 * 1, \mathrm{~F}_{\mathrm{Bz}, \mathrm{z}}(2 \mathrm{t})\right\}+\mathrm{F}_{\mathrm{Bz}, \mathrm{z}}(\phi(\mathrm{t})) * 1 * 1 * \mathrm{~F}_{\mathrm{Bz}, \mathrm{z}}(2 \phi(\mathrm{t})) \\
& \mathrm{F}_{\mathrm{Bz}, \mathrm{z}}(\mathrm{t})+\alpha \mathrm{F}_{\mathrm{Bz}, \mathrm{z}}(\mathrm{t}) \geq \alpha \mathrm{F}_{\mathrm{Bz}, \mathrm{z}}(2 \mathrm{t})+\mathrm{F}_{\mathrm{Bz}, \mathrm{z}}(\phi(\mathrm{t})) * \mathrm{~F}_{\mathrm{Bz}, \mathrm{z}}(2 \phi(\mathrm{t})) \\
& \mathrm{F}_{\mathrm{Bz}, \mathrm{z}}(\mathrm{t})+\alpha \mathrm{F}_{\mathrm{Bz}, \mathrm{z}}(\mathrm{t}) \geq \alpha\left\{\mathrm{F}_{\mathrm{Bz}, \mathrm{z}}(\mathrm{t}) * \mathrm{~F}_{\mathrm{z}, \mathrm{z}}(\mathrm{t})\right\}+\mathrm{F}_{\mathrm{Bz}, \mathrm{z}}(\phi(\mathrm{t})) * \mathrm{~F}_{\mathrm{Bz}, \mathrm{z}}(\phi(\mathrm{t})) * \mathrm{~F}_{z, z}(\phi(\mathrm{t})) \\
& \mathrm{F}_{\mathrm{Bz}, \mathrm{z}}(\mathrm{t})+\alpha \mathrm{F}_{\mathrm{B} z, z}(\mathrm{t}) \geq \alpha\left\{\mathrm{F}_{\mathrm{Bz}, z}(\mathrm{t}) * 1\right\}+\mathrm{F}_{\mathrm{Bz}, \mathrm{z}}(\phi(\mathrm{t})) * 1 \\
& \mathrm{~F}_{\mathrm{Bz}, \mathrm{z}}(\mathrm{t})+\alpha \mathrm{F}_{\mathrm{Bz}, \mathrm{z}}(\mathrm{t}) \geq \alpha \mathrm{F}_{\mathrm{Bz}, \mathrm{z}}(\mathrm{t})+\mathrm{F}_{\mathrm{Bz}, \mathrm{z}}(\phi(\mathrm{t})) \\
& \mathrm{F}_{\mathrm{Bz}, \mathrm{z}}(\mathrm{t}) \geq \mathrm{F}_{\mathrm{Bz}, \mathrm{z}}(\phi(\mathrm{t}))
\end{aligned}
$$

which is a contradiction and we get $\mathrm{Bz}=\mathrm{z}$ and so

$$
\mathrm{z}=\mathrm{ABz}=\mathrm{A} z .
$$

Therefore, $\mathrm{Pz}=\mathrm{Az}=\mathrm{Bz}=\mathrm{z}$.
Combining the results from different steps, we get

$$
\mathrm{Az}=\mathrm{Bz}=\mathrm{Pz}=\mathrm{Qz}=\mathrm{Tz}=\mathrm{Sz}=\mathrm{z} .
$$

Hence, the six self maps have a common fixed point in this case.
Case when $P(X)$ is complete follows from above case as $P(X) \subseteq S T(X)$.
Case II. $\mathbf{A B}(\mathbf{X})$ is complete. This case follows by symmetry. As $\mathrm{Q}(\mathrm{X}) \subseteq \mathrm{AB}(\mathrm{X})$, therefore the result also holds when $\mathrm{Q}(\mathrm{X})$ is complete.

## Uniqueness:

Let $\mathrm{z}_{1}$ be another common fixed point of $\mathrm{A}, \mathrm{B}, \mathrm{P}, \mathrm{Q}, \mathrm{S}$ and T . Then
$\mathrm{Az}=\mathrm{Bz}_{1}=\mathrm{Pz}_{1}=\mathrm{Sz}=\mathrm{T} z_{1}=\mathrm{Qz} z_{1}=z_{1}$, assuming $\mathrm{z} \neq \mathrm{z}_{1}$.
Put $x=z$ and $y=z_{1}$ in (3.1.5), we get

$$
\begin{aligned}
& \left.\left[1+\alpha \mathrm{F}_{\mathrm{ABz}, \mathrm{STz}}^{1} \mathrm{t}\right)\right]{ }^{*} \mathrm{~F}_{\mathrm{Pz}, \mathrm{Q} z_{1}}(\mathrm{t}) \\
& \geq \alpha \min \left\{\mathrm{F}_{\mathrm{Pz}, \mathrm{ABz}}(\mathrm{t}) * \mathrm{~F}_{\mathrm{Qz}_{1}, \mathrm{STz}}^{1} 2(\mathrm{t}), \mathrm{F}_{\mathrm{Pz}, \mathrm{STz}}^{1} 2(2 \mathrm{t}) * \mathrm{~F}_{\mathrm{Qz}_{1}, \mathrm{ABz}}(2 \mathrm{t})\right\} \\
& \left.+\mathrm{F}_{\mathrm{ABz}, \mathrm{STz}}^{1} 10(\mathrm{t})\right) * \mathrm{~F}_{\mathrm{Pz}, \mathrm{ABz}}(\phi(\mathrm{t})) * \mathrm{~F}_{\mathrm{Qz}_{1}, \mathrm{STz}_{1}}(\phi(\mathrm{t})) * \mathrm{~F}_{\mathrm{Pz}, \mathrm{ST} z_{1}}(2 \phi(\mathrm{t})) * \mathrm{~F}_{\mathrm{Qz}_{1}, \mathrm{ABz}}(2 \phi(\mathrm{t})) \\
& {\left[1+\alpha \mathrm{F}_{z, z_{1}}(\mathrm{t})\right] * \mathrm{~F}_{\mathrm{z}, \mathrm{z}_{1}}(\mathrm{t})} \\
& \geq \alpha \min \left\{\mathrm{F}_{z, z}(\mathrm{t}) * \mathrm{~F}_{z_{1}, z_{1}}(\mathrm{t}), \mathrm{F}_{z, z_{1}}(2 \mathrm{t}) * \mathrm{~F}_{\mathrm{z}_{1}, z}(2 \mathrm{t})\right\}+\mathrm{F}_{z, z_{1}}(\phi(\mathrm{t})) * \mathrm{~F}_{\mathrm{z}, \mathrm{z}}(\phi(\mathrm{t})) \\
& \text { * } \mathrm{F}_{z_{1}, z_{1}}(\phi(\mathrm{t})) * \mathrm{~F}_{\mathrm{z}, \mathrm{z}_{1}}(2 \phi(\mathrm{t})) * \mathrm{~F}_{z_{1}, z}(2 \phi(\mathrm{t})) \\
& \mathrm{F}_{\mathrm{z}, \mathrm{z}_{1}}(\mathrm{t})+\alpha\left\{\mathrm{F}_{z, z_{1}}(\mathrm{t}) * \mathrm{~F}_{\mathrm{z}, \mathrm{z}_{1}}(\mathrm{t})\right\} \geq \alpha \min \left\{1, \mathrm{~F}_{z, z_{1}}(2 \mathrm{t})\right\}+\mathrm{F}_{\mathrm{z}, \mathrm{z}_{1}}(\phi(\mathrm{t})) * \mathrm{~F}_{\mathrm{z}, \mathrm{z}_{1}}(2 \phi(\mathrm{t})) \\
& \left.\mathrm{F}_{z, z_{1}}(\mathrm{t})+\alpha \mathrm{F}_{z, z_{1}}(\mathrm{t}) \geq \alpha \mathrm{F}_{z, z_{1}}(2 \mathrm{t})\right\}+\mathrm{F}_{z, z_{1}}(\phi(\mathrm{t})) * \mathrm{~F}_{\mathrm{z}, \mathrm{z}_{1}}(\phi(\mathrm{t})) * \mathrm{~F}_{z, \mathrm{z}}(\phi(\mathrm{t}))
\end{aligned}
$$

$$
\begin{aligned}
& \mathrm{F}_{z_{1}, z}(\mathrm{t})+\alpha \mathrm{F}_{z_{1}, z}(\mathrm{t}) \geq \alpha\left\{\mathrm{F}_{z_{1}, z}(\mathrm{t}) * \mathrm{~F}_{z_{, z}}(\mathrm{t})\right\}+\mathrm{F}_{z_{1}, z}(\phi(\mathrm{t})) * 1 \\
& \mathrm{~F}_{z_{1}, z}(\mathrm{t})+\alpha \mathrm{F}_{z_{1}, z}(\mathrm{t}) \geq \alpha \mathrm{F}_{z_{1}, z}(\mathrm{t})+\mathrm{F}_{z_{1}, z}(\phi(\mathrm{t})) \\
& \mathrm{F}_{z_{1}, z}(\mathrm{t}) \geq \mathrm{F}_{z_{1}, z}(\phi(\mathrm{t}))
\end{aligned}
$$

which is a contradiction.
Hence $\mathrm{z}=\mathrm{z}_{1}$ and so z is the unique common fixed point of $\mathrm{A}, \mathrm{B}, \mathrm{S}, \mathrm{T}, \mathrm{P}$ and Q .
This completes the proof.
Remark 3.1. If we take $\mathrm{B}=\mathrm{T}=\mathrm{I}$, the identity map on X in theorem 3.1, then condition (3.1.2) is satisfied trivially and we get
Corollary 3.1. Let $\mathrm{A}, \mathrm{S}, \mathrm{P}$ and Q be self mappings on a Menger space ( $\mathrm{X}, \boldsymbol{F},{ }^{*}$ ) with continuous t norm $*$ satisfying :
(i) $\quad P(X) \subseteq T(X), Q(X) \subseteq A(X)$;
(ii) One of $\mathrm{S}(\mathrm{X}), \mathrm{Q}(\mathrm{X}), \mathrm{A}(\mathrm{X})$ or $\mathrm{P}(\mathrm{X})$ is complete;
(iii) The pairs $(\mathrm{P}, \mathrm{A})$ and $(\mathrm{Q}, \mathrm{S})$ are occasionally weak compatible;
(iv) $\left[1+\alpha \mathrm{F}_{\mathrm{Ax}, \mathrm{Sy}}(\mathrm{t})\right] * \mathrm{~F}_{\mathrm{Px}, \mathrm{Qy}}(\mathrm{t}) \geq \alpha \min \left\{\mathrm{F}_{\mathrm{Px}, \mathrm{Ax}}(\mathrm{t}) * \mathrm{~F}_{\mathrm{Qy}, \mathrm{Sy}}(\mathrm{t}), \mathrm{F}_{\mathrm{Px}, \mathrm{Sy}}(2 \mathrm{t}) * \quad \mathrm{~F}_{\mathrm{Qy}, \mathrm{Ax}}(2 \mathrm{t})\right\}$

$$
\begin{aligned}
& +\mathrm{F}_{\mathrm{Ax}, \mathrm{Sy}}(\phi(\mathrm{t})) * \mathrm{~F}_{\mathrm{Px}, \mathrm{Ax}}(\phi(\mathrm{t})) * \mathrm{~F}_{\mathrm{Qy}, \mathrm{Sy}}(\phi(\mathrm{t})) * \mathrm{~F}_{\mathrm{Px}, \mathrm{Sy}}(2 \phi(\mathrm{t})) \\
& * \mathrm{~F}_{\mathrm{Qy}, \mathrm{Ax}}(2 \phi(\mathrm{t}))
\end{aligned}
$$

for all $\mathrm{x}, \mathrm{y} \in \mathrm{X}, \mathrm{t}>0$ and $\phi \in \mathrm{E}$.
Then $\mathrm{A}, \mathrm{S}, \mathrm{P}$ and Q have a unique common fixed point in X .
Remark 3.2. In view of remark 3.1, corollary 3.1 is a generalization of the result of Pathak and Verma [1] in the sense that both the pair of self maps has been restricted to occasionally weak compatibility and we have dropped the condition of continuity in a Menger space with continuous tnorm.

## References

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