International Journal of Scientific and Innovative Mathematical Research (IJSIMR) Volume 2, Issue 2, February 2014, PP 221-232 ISSN 2347-307X (Print) & ISSN 2347-3142 (Online) www.arcjournals.org

Parametric Fitting of Non – Function – Like Curves by Minmaxion and Minaddition

CHILLARA SOMASHEKAR

Department of Mathematics Bharat Institute of Engg.&Tech Hyderabad, Andhra Pradesh India chillara.somashekar@gmail.com

S N N PANDIT

Center for Quantitative Methods Osmania University Hyderabad India

SIVA RAMA KRISHNA REDDY V

Department of Mathematics St. Marys College of Engg. & Tech. Hyderabad, Andhra Pradesh India srkreddy.vemireddy@gmail.com

S RAMAMURTHY

Professor of Mathematics GokarajuRangarajuInst of Engg.&Tech Hyderabad, Andhra Pradesh India

Abstract:*It has been the desire of every Scientist or Engineer to give precise mathematical formulations to the model he envisages. The model could represent some physical, biological or sociological process.*

Fitting curves to complex shapes has always been a challenging problem and continues to be so. While global fits to such data cannot serve the purpose, one usually thinks of piecewise fitting strategies. Even then, each curve segment may have a lot in detail and hence fitting an explicit equation to it may not produce the desired shape. Other options include (a) a parametric representation to a curve segment and (b) a multi-resolution representation using wavelets.

Given a discrete set of n points (x_i, y_i) , i = 1: none can guess what the curve that fits the points looks like. In many applications, the data that are captured from physical or biological experiments do not have simple structures in the sense that, if one were to fit a curve to this data, the curve would not appear as a function in the classical sense. Further, in most such situations, the genesis of the data is unknown.

The modeller will have to address two questions: (a) ordering the points and (b) to give an analytic expression to the approximating curve. The resulting fitted curve must not only conform to statistical standards but also appear pleasing to the eye; it should essentially capture the shape of the data.

Parametric representation to a curve segment by a novel approach is being explored. The technique is purely data-guided and performs a dual role: ordering of points in the data set and parameterization leading to a fit of good quality.

This approach requires the use of two matrix operations namely minmaxion and minaddition. As these are nascent, their definitions and some of their relevant properties are given below.

Definition-I: Minmaxion

Cis min-max product of A and B

 $C\underline{\Delta}A \otimes Bwherec_{ij} = min_x \{max [a_{ix}, b_{xj})\}$

Definition-Ii: Minaddition

C is min-ad product of A and B

 $C\underline{\Delta}A \oplus B \text{where} c_{ij} = min_x \{max [a_{ix} + b_{xj})\}$

Both minmaxion and minaddition are similar to the usual matrix multiplication, satisfy the associative law, are non-commutative, satisfy the power law for square matrices and obey the transposition rule analogous to conventional matrix multiplication.

Another property of minmaxion and minaddition is "satiety" which holds in the case of zero diagonal matrices with non-negative entries. By satiety we mean, if A is a zero diagonal matrix of order n such that $A^{k+1} = A^k$ for some positive integer k < n, we say A^k is the satiated matrix of A.

The concepts of approachability distance and connective distance between node pairs, crucial to this procedure, is introduced through the satiety property of minmaxion and minaddition.

These new distances are instrumental in imputing an ordering among intermediate points connecting node pairs. Further, we propose the ordering index itself as the parameter for curve fitting.

As a test case this procedure has been applied on a data set. Ordering of the points as well as parametric fitting proved satisfactory, albeit for one class of curves possessing lineal shapes

Keywords and Phrases: Analytic expression, parameterization, ordering of points, MINMAXION, MINADDITION, approachability distance, connective distance, ordering index.

1. INTRODUCTION

Recognition of objects has been one of the challenges in several areas of image analysis like biomedical image analysis, biometrics, military target recognition and general computer vision.

There are many applications where image analysis can be reduced to the analysis of shapes. To describe shape through object boundary is a preliminary but crucial step in the overall description of the shape.

We have intuitive ideas about curves because of their striking visual nature. A curve, in general, has no simple mathematical definition. Given a discrete set of n data points (x_i, y_i) , i=1:n, one can guess what the curve that fits the points should looks like. We fit the data either by means of interpolants or by approximating curves.

In many applications, the data that are captured from physical or biological experiments do not have simple structures in the sense that, if one were to fit a curve to this data, the curve would not appear as a *function* in the classical sense. Figure 1 shows two typical curves which are not function-like. A global explicit fit to such complicated shapes is impossible. These curves do not qualify to be called functions.



Figure 1. Curves which are not functions

One usual approach is to describe the overall shape by a piecewise approximation technique. Several strategies have been suggested which include segmenting the curves at points of high curvature and then going for a piecewise fit of each segment. One then may have to express such curve segments either implicitly, or through parameterization. The implicit form of representing curves does not have this limitation. Conic sections are classic examples where the implicit form has been successfully tried.

Fundamentally, one has to answer the question of *ordering* the points. This is particularly true of situations where we have no idea of how the data were generated.

The parametric form is preferred to fit closed and multiple valued curves. Since a point on a parametric curve is specified by a single value of a parameter, the parametric form is, in a sense, axis independent.

In the parametric form, each coordinate of a point on a curve is represented as a function of a single parameter t. For a two dimensional curve with t as a parameter, the Cartesian coordinates of a point on the curve are given by x = x(t), y = y(t); $a \le t \le b$.

There is no unique parametric representation of a curve. For example,

$$x = \cos\theta$$
, $0 \le \theta \le \frac{\pi}{2}$, $y = \sin\theta$, $0 \le \theta \le \frac{\pi}{2}$

And

$$x = \frac{1 - t^2}{1 + t^2}$$
, $0 \le t \le 1$, $y = \frac{2t}{1 + t^2}$, $0 \le t \le 1$,

are two different parameterizations of the unit circular are in the first quadrant.

The curve end points and the length are fixed by the parameter range. Often it is convenient to normalize the parameter range for the curve segment of interest to $0 \le t \le 1$.

We introduce a new parameterization procedure. This procedure requires the use of two matrix operations namely MINMAXION and MINADDITION [3, 4, 5, 6, and 8]. Since these are nascent, we shall first present their definitions and some of their relevant properties . Thereafter; we shall show how these operations will be useful in the context of curve parameterization.

2. MINMAXION AND MINADDITION

Definition I: (MINMAXION).*C* is the min-max product of *A* and *B*

$$C \triangleq A \otimes B$$
 where $c_{ij} = min_x \{max \ (a_{ix}, b_{xj})\}.$

Definition II : (MINADDITION). C Is the min-ad product of A and B

$$C \triangleq A \oplus B$$
 where $c_{ij} = min_x \{max \ (a_{ix} + b_{xj})\}.$

Both MINMAXION and MINADDITION are similar to the usual matrix multiplication, satisfy the associative law, are non-commutative, satisfy the power law for square matrices and obey the transposition rule analogous to conventional matrix multiplication.

Another property of minmaxion and minaddition is "satiety" which holds in the case of zero diagonal matrices with non-negative entries. By satiety we mean, if A is a zero diagonal matrix of order n such that $A^{k+1} = A^k$ for some positive integer k < n, we say A^k is the satiated matrix of A. In fact, one can define satiated minmaxion and satiated minaddition when the zero-diagonal matrix D = [dij] is not symmetric. Further, it is not necessary that the d_{ij} satisfy the usual metric laws, even though in the present context they are Euclidean distances.

2.1. MOTIVATION FOR THE MINMAXION AND MINADDITION OPERATIONS

Consider a network with n points where the direct distance between each point pair (i,j) is d_{ij} . As mentioned earlier, the d_{ij} 's need not be "metric". They need not be even symmetric. They can be any "scalars" allowing comparison (<,=,> between two d_{ij} 's) and addition. For instance, d_{ij} may be the time taken from hilltop i to the base j or the cost of going from *itoj*. Now consider a path *ij* through these points in r steps i.e. $a = x_1 \rightarrow x_2 \rightarrow \cdots \rightarrow x_{r+1} = b$. The *approachability distance* for this path is defined as the largest of the distances between the consecutive point pairs along the path. Among all the paths of the same number of steps r, there will be at least one path for which the approachability distance is minimum. This is defined as the *connective distance* for the step length r.

The smallest among these $(r = 1 : \dots : n - 1)$ distances is defined as the connective distance. It can be easily seen that the minmax power sequence is term-wise monotonic. The connective distance of step length r is given by $a^{(r)}_{ij}$ and the elements of the satiated minmaxion matrix give the (overall) connective lengths between the node pairs. Similarly, in case of minaddition, the

satiated matrix gives the length of the total distance along the shortest paths between the ordered node pairs. One may refer to, Reddy [8].

2.2. ORDERING THE POINTS AND PARAMETERIZATION BY MINMAXION AND MINADDITION

Consider a test curve on which we take a discrete set of points. Once we have the co-ordinates of the point-pairs, we can compute inter-node distances d_{ij} (say, Euclidean distances) and store these distances in the distance matrix D.

$$D = \begin{bmatrix} d_{ij} \end{bmatrix} = \begin{cases} 0 & , & i = j \\ > 0 & , & i \neq j \end{cases}$$

Let $S = D^*$ be the minmax satiated matrix of D, i.e. $D^* = D^r = D^{r+1}$ for some r < n. The element d_{ij}^* of D^* gives the $(r^{th}$ order) connective distance from *i* to *j*. Each of these paths will have a link of largest length. Then d_{ij}^* is the smallest among these largest links in the different paths. Let p_{ij}^* be the number of steps from *i* to *j* along this optimal path. The number and the actual path itself can be obtained by the use of minaddition.

One can now define the Direct Link Matrix P from the matrix S as follows.

$$P = [p_{ij}] = \begin{cases} 0 & i = j, \\ 1 & d_{ij} = s_{ij}, i \neq j \\ \infty & otherwise \end{cases}$$

The minad satiated matrix of P, denoted by P^* called the step length matrix, gives the number of steps between point-pairs along these paths. Choosing a point-pair with largest step length, say $\alpha to\beta$, one gets the path from $\alpha to\beta$ on which a relatively large number of points lie in an ordered fashion; the number of steps between any point-pair along this path will be less than this number and one can take this path as an arterial path along which many points lie in a well-defined sequence. If it so happens that, $P^*_{\alpha\beta} = (n-1)orP^*_{\alpha\beta} \sim (n-1)$ one may infer that nodes $\alpha to\beta$ are the end points of a long connective path. Since the sequence of points between $\alpha to\beta$ is now available, one can accept this sequence of points along this path as the appropriate *ordering* among the n points.

Ordering of points along a curve, in general a difficult problem by itself has now been addressed, particularly in the case of open curves, what remains to be tackled is curve parameterization.

We propose the *ordering index* of the connective path itself as the parameter t. The coordinates x(t) and y(t) can now be fitted as functions of 't'. Of course, 't' is in the ordinal scale; but as a first approximation, can be used as values in an interval scale.

The present study investigates curves which are not closed and are in a sense, convex.

Illustration. This is generated as 31 points on the curve $y = sign\left(\frac{x}{3}\right)$. $sin\mathbb{R}2.x$) in the range 0.1 : 0.2 : 0.61 and subjecting the curve to rotation through 36°, getting the *new* as [u(i), v(j)], i = 0 : 30. These values are presented as Table I(a) and (b) and are graphically represented in Figure II(a) and (b), respectively.

Consider the data set given in *Table I(a)*. This set is plotted as a scatter plot in *Figure II(a)*. This set is actually obtained by evaluating y as the function $y = sign\left(\frac{x}{3}\right) . sin(2.x)$ in the range 0.1:0.2: 0.61. *Figure II (b)* (and the corresponding Table I (b) are the plotted values of (u, v) got by a rotation of the data (x, y) by 36°. It is seen that x is not a function of y: neither u is a function of v.

Matrix I (a) gives D, the (squared) Euclidean distance matrix between the points in Table I(a).

Matrix I (b) gives $S = D^*$, *Minmax* satiated matrix for *D*.

Matrix I(c) is the *Minad* satiated matrix P^* for P. P^* is the *direct link matrix*

From *Matrix I(c)*, it can be observed that the largest path length is 30 from i = 1 toj = 9. The optimal (Minmax) path from 1 to 9 is

Parametric Fitting of Non – Function – Like Curves by Minmaxion and Minaddition

 $\begin{matrix} [1 \rightarrow 11 \rightarrow 3 \rightarrow 4 \rightarrow 29 \rightarrow 23 \rightarrow 12 \rightarrow 30 \rightarrow 2 \rightarrow 15 \rightarrow 14 \rightarrow 27 \rightarrow 28 \rightarrow 7 \rightarrow 17 \rightarrow 16 \rightarrow 20 \rightarrow 24 \rightarrow 26 \rightarrow 10 \rightarrow 22 \rightarrow 21 \rightarrow 6 \rightarrow 5 \rightarrow 18 \rightarrow 31 \rightarrow 13 \rightarrow 19 \rightarrow 8 \rightarrow 25 \rightarrow 9 \end{matrix}$

This path covers all the points 0, 1, . . ., 30 and hence is the arterial path. The sequence given by this path is x (t), y (t), t = 0 to 30, the same as the coordinates of the points in the sequence above. The ordering indices shown above can now be used to determine new parameters t_1 and t_2 as described below.

Table 1. (**x**,**y**):Set of 31 points on the curve $y = sign\left(\frac{x}{3}\right) \cdot sin\mathbb{Z}2.x$)in the range [0.1, 6.1] (**u**,**v**):Setofcorresponding 31 pointsafter the dataisrotatedby3ss

X	у	u	V
0.1000	0.1987	0.5746	0.2805
0.3000	0.5646	3.7454	-3.8618
0.5000	0.8415	4.7244	-3.8753
0.7000	0.9854	3.8699	-1.6489
0.9000	0.9738	3.9104	-1.9333
1.1000	0.8085	1.1775	-1.6118
1.3000	0.5155	3.8828	-2.3116
1.5000	0.1411	3.8169	-2.7425
1.7000	-0.2555	0.1977	0.1019
1.9000	-0.6119	3.5216	-1.4477
2.1000	-0.8716	2.0731	-2.0804
2.3000	-0.9937	1.7301	-2.2122
2.5000	-0.9589	1.1455	0.3858
2.7000	-0.7728	3.2177	-1.5257
2.9000	-0.4646	1.2251	-1.2060
3.1000	-0.0831	1.1866	-1.9395
3.3000	0.3115	1.3547	-0.3471
3.5000	0.6570	1.2965	-0.7675
3.7000	0.8987	1.3005	0.2589
3.9000	0.9985	2.4591	-1.8894
4.1000	0.9407	3.7146	-3.5639
4.3000	0.7344	3.7488	-3.1766
4.5000	0.4121	0.8991	0.3869
4.7000	0.0248	2.8529	-1.6876
4.9000	-0.3665	1.3651	0.0075
5.1000	-0.6999	4.0710	-4.0941
5.3000	-0.9228	4.3656	-4.0290
5.5000	-1.0000	1.2767	-2.1558
5.7000	-0.9193	1.4589	-2.2452
5.9000	-0.6935	3.8618	-4.0418
6.1000	-0.3582	3.7421	-1.4845



Figure 2.

The curve fitting of u and v as functions of t is in two stages. Initially, t is the ordinal index and we take the coordinates of the beginning an end points in the ordered curve as (u_b, u_e) and (v_b, v_e) respectively. We then convert this index t which has the range $0:30 \ tot_1 = u_b + (0:30) \times (u_e - u_b)/3$ and $t_2 = v_b + (0:30) \times (v_e - v_b)/30$. Using these t_1 and t_2 as independent variables and getting the co-ordinates of $u(t_1)$ and $v(t_2)$ as the curves to be fitted to, we go for successive polynomial fits. A scatter plot of the vectors x and y gives the theoretical fitted approximating curves.

The fitted polynomials $u(t_1)$, $v(t_2)$ are given as parametric equations below. These are plotted, along with the residuals in FigureIII (a) and (b).

In the range $0.1977 \le t_1 \le 4.7244$

$$u(t_1) = \begin{cases} 0.1731 t_1 + 0.9490 \\ 0.1546t_1^2 + 0.9705 t_1 - 0.0044 \\ 0.7766t_1^3 - 0.3826t_1^2 + 0.6663t_1 + 0.0908 \\ 0.6396t_1^4 + 0.0759t_1^3 + 0.2700t_1^2 + 0.0323t_1 - 0.0125 \\ -1.5276t_1^5 + 10.0261t_1^4 - 12.6001t_1^3 + 6.7478t_1^2 - 1.5278t_1 + 0.1231 \end{cases}$$

Similarly, in the range $-3.8753 \le t_2 \le 0.1019$

$$v(t_2) = \begin{cases} 0.2162t_2 + 1.0799\\ 0.1994t_2^2 + 1.0506t_2 - 0.0078\\ 0.5584t_2^3 + 2.5530t_2^2 + 1.0355t_2 + 0.1843\\ 0.5192t_2^4 + 2.1697t_2^3 + 0.5225t_2^2 - 0.0337t_2 - 0.0289\\ 0.3549t_2^5 - 3.5900t_2^4 - 12.6836t_2^3 - 10.0490t_2^2 - 3.0827t_2 - 0.3237 \end{cases}$$

0.727	4266	17.3	13.67	6.495	3.269	22076	0,605	20.06	18.76	1.963	1.386	2.61	1.928	7399	11.82	21.41	8.192	1.353	2.275	10.25	1.619	2.21	0.18	1.053	1.49	5.414	15.57	2327	0.197	0
0.167	4.073	14.99	11.76	6.413	2.882	8.236	1.492	17.83	16.44	2.766	0.539	1.99	0.905	7.191	10.25	19.37	1.74	2.54	1.268	6/0/6	2.633	1.135	0.755	2.151	2.643	5.332	13.41	1.484	0	0.197
1.022	1.618	21012	4.895	3.141	0.762	3.329	4.861	9.052	8.047	8.78	0.806	0.186	970	3.415	4.01	10.25	3.398	6.943	0.135	3.479	7.819	0.404	3.521	690.9	7.466	2,499	5.97	0	1.484	2.327
11.66	5.736	91-01-0	00.0	5.651	5.524	2,422	20.64	0.413	0.16	28.3	10.24	5.545	9,016	4.913	0.469	0:959	3.746	24.8	6.783	1.238	17.77	1.841	18.07	22.96	26.15	5.878	0	5.97	13.41	15.57
5.522	0.098	6.845	4.515	0.05	0.505	0.877	6.768	7.375	7.305	13.45	5.694	1324	5.541	0.162	3.041	134	0.387	9006	3.794	1.764	11.67	4.891	5.907	7.846	10.24	0	5.878	2.499	5.332	5.414
4.072	9.034	28.39	23.54	11.58	8.121	16.18	0.361	31.52	30.14	0.573	5.495	7.615	6.608	12.97	20.82	32.8	14.45	0.061	7.446	18.31	0.117	1971	952.0	0.178	0	10.24	26.15	7.466	2.643	1.49
3.514	6.86	25.06	20.44	100.9	6.199	13.28	29010	27.78	26.62	1.241	4.846	5.957	5.831	10.24	17.8	23.81	11.62	1 0:0	6291	15.34	0.527	6.296	0.37	0	0.178	3446	22.96	690.9	2.151	1.053
1.631	4.86	19.94	15.92	6.993	4.042	10.25	0.126	22.62	21.42	1.54	2.564	3.598	3.278	8.021	13.74	23.8	9.048	0.581	3.62	11.8	1.002	3.614	0	0.37	0.746	5.907	18.07	3.521	0.755	0.18
0.48	3.611	9,002	6.827	5.792	2.254	5.88	5.004	11.63	10.24	17	0.168	1.127	0.041	6.169	6.111	13.32	6.107	7.021	0.075	5.808	7.161	0	3.614	6.296	7.241	4.891	1987	101-104	1.135	2.21
3.944	10.25	29.49	34.64	13.15	9076	17.66	66970	32.94	31.36	0.174	5.303	8.26	6.428	14.58	22.03	34.49	16.03	1337	1,549	19.65	0	7.161	1.002	0.527	0.117	11.67	27.21	7.819	2.633	1.619
8.245	1.84	1.69	0.685	1.588	2.042	0.19	13.57	1.956	1.891	21.19	7.563	2.572	797.9	1.199	0.193	2.107	0.664	16.92	4.636	0	19.65	5.808	11.8	15.34	18.31	1.764	1.258	3.479	62076	10.25
0.666	2.684	7,892	5.765	4.578	1.536	4.644	5.06	10.25	120.6	10/2	0.37	0.636	0.209	4.896	5.015	11.73	4.832	16012	0	4.636	1.549	570.0	3.62	6.291	7.446	3.7%	6.783	0.135	1.268	2.275
3.991	2.948	26.98	222	10.24	7.214	14.77	161.0	29.86	28.63	62610	5.409	6.912	172-0	11.56	19.47	30.97	13.02	0	16012	16.92	0.337	120.7	0.561	1 0.04	0.061	800.6	24.8	6.943	254	1.353
7.572	0.646	448	2.697	0.23	1179	0.144	10.25	4.599	4.695	17.93	7.419	2.108	6.986	0.083	1.572	4434	0	13.02	4832	0.664	16.03	6.107	9.048	11.62	14.45	0.387	3.746	3.398	1.74	8.192
17.7	162.7	0.772	1117	6.681	8.289	3.153	26.36	0.152	0.475	36.31	16.26	9/0/6	14.84	2.687	1.44	0	4434	30.97	11.73	2.107	34.49	13.32	23.8	23.81	32.8	HC17	0.959	10.25	19.37	21.41
90.6	3.007	0.761	0.151	2.863	3.02	0.766	15.82	1.107	946.0	23.36	8.095	3.32	7.153	2.349	0	14	1.572	19.47	5.005	0.193	22.03	6.111	13.74	17.8	20.82	3.041	0.469	4.01	10.25	11.82
7.251	0.441	5.726	3.692	0.043	1.036	0.439	9.017	5.911	6.02	16.35	7.284	2.048	6.982	0	2.349	5.687	0.083	11.56	4.896	1.199	14.58	6.169	8.021	10.24	12.97	0.162	4.913	3.415	161.7	1.399
0.306	4.165	10.24	7.926	6259	2.704	6.816	4.688	13.05	11.57	6.262	0.055	1.469	0	6.982	7.153	14.84	6.986	6.477	602.0	262.9	6.428	0.041	3.278	5.831	6.608	5,541	9,005	0.64	0.905	1.928
1.72	0.708	6.601	438	181	0.196	2.205	4.795	8.213	7.459	62016	1.622	0	1.469	2.048	3.32	9/0/6	2.108	6.902	0.636	2.572	8.26	1.127	3.598	5.957	7.615	1.304	5,545	0.186	1.99	2.61
0107	4.207	11.58	9.029	6.737	2.84	7.408	3.823	14.47	12.96	5.145	0	1.622	0.055	1.284	8.095	16.26	7.419	5.409	0.37	7.563	5.303	0.168	2.564	4.846	5.495	5.694	10.24	0.806	0.539	1.386
3.897	11.77	30.6	25.81	15.08	10.25	19.41	1372	31.44	32.61	0	5.145	62076	6.262	16.55	23.36	36.31	17.93	0.979	¥02.7	21.19	0.174	17	154	1241	0.573	13.45	28.3	8.28	2.766	1.963
14.53	2222	0.047	30F.0	6.918	7.275	3.213	24.15	0.091	0	32.61	12.96	7.459	11.57	6.02	0.946	97£0	4.695	28.63	120'6	1,891	31.36	10.24	21.42	26.62	30.14	7.305	0.16	8.047	16.44	18.76
16.01	7.584	0.254	0.64	6.863	LLL	3.182	25.3	0	0.091	新麗	14.47	8.213	13.05	5.911	1.107	0.152	4.599	29.86	10.25	1.956	32.94	11.63	22.62	27.78	31.52	7.375	0.413	9.052	17.83	20.06
2.657	5.783	22.63	18.28	7.876	5.087	11.72	0	25.3	24.15	1372	3.823	4.795	4.683	9.017	15.82	26.36	10.25	161.0	5.06	13.57	0.699	5.084	0.126	29010	0.361	6.768	20.64	4.861	1.492	0.605
7.809	1.06	2.994	1.597	0.704	1.45	0	11.72	3.182	3.213	19.41	7.408	2.205	6.816	0.439	0.766	3.153	0144	14.77	464	0.19	17.66	5.88	10.25	13.28	16.18	0.877	2.422	3.329	8.286	9.073
2.813	0.159	92'9	4.263	0.832	0	1.45	5.087	LL	7.205	10.25	2.84	0.196	2.704	1.036	3.02	8.289	1179	7.214	1.536	2.042	9.064	2.254	400	6199	8.121	0.505	5.524	0.762	2.882	3.269
6.593	112.0	6.554	4.325	0	0.832	0.704	7.876	6.863	6.918	15.08	6.737	1.81	6.529	0.043	2.863	6.681	0.23	10.24	4.578	1.588	13.15	5.792	6.993	9.001	11.58	0.05	5.651	3.141	6.413	6.495
10.25	4.401	0.25	0	4.325	4.263	1.597	18.28	970	0.408	25.81	67076	438	7.926	3.692	0.151	1117	2.697	222	5.765	0.685	34.64	6.827	15.92	20.44	23.54	4.515	0.09	4.895	11.76	13.67
13.11	6.746	0	0.25	6.554	6.56	2.994	22.63	0.254	0.047	30.6	11.58	109.0	10.24	5.726	0.761	0.772	4.448	26.98	7,892	1.69	29.49	9.002	19.94	25.06	28.39	6.845	97010	21047	14.99	17.3
417	0	6.746	4.401	11270	0.159	1.06	5.783	7.504	1325	11.77	4.297	902.0	4.165	0.441	3.007	167.7	97970	7.948	2.684	184	10.25	3.611	4.86	6.36	9.034	360.0	5.736	1.618	4.073	4.266
0	4.17	13.11	10.25	6.593	2.813	7.809	2.657	10.01	14.53	3.897	20110	1.72	0.306	7.251	90'6	17.71	7.572	3.991	0.666	8.245	3.944	0.48	1.631	3.514	4072	5.522	11.66	1.022	791.0	0.727

Matrix I (a)

Matrix of (squared) distances between the 31 points in pairs

701.0	701.0	701.0	701.0	0.197	701.0	0.197	0.18	701.0	761.0	0.18	701.0	701.0	0.197	0.197	701.0	0.197	701.0	0.18	0.197	701.0	0.18	701.0	0.18	0.18	0.18	0.197	701.0	701.0	701.0	0
291-0	0.196	961.0	961.0	0.196	0.196	0.196	261-0	0.196	0.196	26110	29110	0.186	29110	0.196	0.196	0.196	0.196	261-0	291-0	0.196	26110	29110	26110	261-0	26110	0.196	0.196	29110	0	26110
0.135	0.196	0.196	0.196	0.196	0.196	0.196	0.197	0.196	0.196	0.197	0.135	0.136	0.135	0.196	0.196	0.196	0.196	0.197	0.135	0.196	701.0	0.135	0.197	0.197	701.0	0.196	0.196	0	0.167	701.0
0.196	0.193	0.046	0.09	0.193	0.193	0.193	0.197	0.091	0.047	0.197	0.196	0.196	0.196	0.193	0.151	0.152	0.193	0.197	0.196	0.193	761.0	0.196	0.197	0.197	0.197	0.193	0	0.196	0.196	0.197
0.196	0.098	0.193	0.193	0.05	0.159	0.144	761.0	0.193	0.193	261.0	0.196	0.196	0.196	0.05	0.193	0.193	0.083	791.0	0.196	61.0	261.0	0.196	261.0	261.0	261.0	0	0.193	0.196	0.196	761.0
701.0	0.197	761.0	701.0	701.0	701.0	0.197	790.0	701.0	701.0	0.174	701.0	701.0	0.197	0.197	701.0	701.0	701.0	0.061	0.197	701.0	711.0	701.0	0.126	0.061	0	701.0	701.0	701.0	701.0	0.18
761.0	761.0	761.0	761.0	761.0	761.0	761.0	0.067	761.0	761.0	0.174	761.0	761.0	0.197	0.197	0.197	761.0	761.0	0.04	761.0	761.0	711.0	761.0	0.126	0	0.061	761.0	761.0	761.0	761.0	0.18
26110	261.0	26110	26110	261.0	26110	261.0	0.126	791.0	261.0	0.174	26110	261.0	261.0	261.0	791.0	261.0	261.0	0.126	261.0	26110	0.126	261.0	0	0.126	0.126	261.0	261.0	26110	26110	0.18
701.0	0.196	0.196	0.196	0.196	0.196	0.196	701.0	0.196	0.196	701.0	0.055	0.136	0.041	0.196	0.196	0.196	0.196	701.0	0.075	0.196	791.0	0	701.0	701.0	701.0	0.196	0.196	0.135	0.167	0.197
761.0	761.0	761.0	761.0	761.0	761.0	761.0	0.117	761.0	701.0	0.174	761.0	761.0	761.0	701.0	761.0	701.0	761.0	0.117	761.0	761.0	0	761.0	0.126	0.117	0.117	761.0	761.0	761.0	761.0	0.18
0.196	0.19	0.193	0.193	0.19	0.19	0.19	791.0	0.193	0.193	261.0	0.196	0.196	0.196	0.19	0.193	0.193	0.19	791.0	0.196	0	26110	0.196	261.0	791.0	261.0	0.19	0.193	0.196	0.196	791.0
201.0	0.196	0.196	0.196	0.196	0.196	0.196	701.0	0.196	0.196	701.0	6.075	0.136	62075	0.196	0.196	0.196	0.196	701.0	0	0.196	261.0	6.075	701.0	701.0	791.0	0.196	0.196	0.135	0.167	761.0
261.0	791.0	261.0	261.0	791.0	261.0	261.0	290.0	761.0	741.0	9/1/4	261.0	791.0	741.0	791.0	741.0	791.0	791.0	0	261.0	261.0	711.0	261.0	0.126	0.04	0.061	791.0	261.0	261.0	261.0	0.18
0.196	0.098	0.193	0.193	0.083	0.159	0.144	701.0	0.193	0.193	701.0	0.196	0.196	0.196	0.083	0.193	0.193	0	701.0	0.196	010	261.0	0.196	701.0	701.0	701.0	0.083	0.193	0.196	0.196	761.0
0.196	0.193	0.152	0.152	0.193	0.193	0.193	701.0	0.152	0.152	0.197	0.196	0.196	0.196	0.193	0.152	0	0.193	0.197	0.196	0.193	761.0	0.196	0.197	0.197	0.197	0.193	0.152	0.196	0.196	761.0
961.0	0.193	0.151	0.151	0.193	0.193	0.193	791.0	0.151	0.151	761.0	0.196	0.196	0.196	0.193	0	0.152	0.193	761.0	0.196	0.193	26110	961.0	761.0	791.0	761.0	0.193	0.151	961.0	0.196	761.0
961.0	360.0	0.193	0.193	0.043	0.159	0.144	0.197	0.193	0.193	701.0	0.196	0.196	0.196	0	0.193	0.193	0.083	701.0	0.196	010	261.0	0.196	701.0	701.0	791.0	0.05	0.193	0.196	0.196	761.0
20110	0.196	0.196	0.196	0.196	0.196	0.196	761.0	0.196	0.196	761.0	0.055	0.186	0	0.196	0.196	0.196	0.196	761.0	0.075	0.196	761.0	0.041	761.0	761.0	761.0	0.196	0.196	0.135	791.0	761.0
0.186	0.196	961.0	961.0	0.196	961.0	0.196	791.0	0.196	0.196	261.0	0.186	0	0.186	0.196	0.196	0.196	0.196	791.0	0.186	961.0	261.0	0.186	261.0	791.0	261.0	0.196	961.0	0.186	0.186	761.0
701.0	0.196	961.0	961.0	0.196	0.196	0.196	701.0	0.196	0.196	701.0	0	0.136	0.055	0.196	0.196	0.196	0.196	701.0	6.075	0.196	261.0	0.055	701.0	701.0	791.0	0.196	0.196	0.135	701.0	761.0
0.197	0.197	0.197	0.197	0.197	0.197	0.197	0.174	0.197	0.197	0	0.197	0.197	0.197	0.197	0.197	0.197	0.197	0.174	0.197	0.197	0.174	0.197	0.174	0.174	0.174	0.197	0.197	0.197	0.197	0.18
961.0	0.193	240.0	0.09	0.193	0.193	0.193	741.0	0.091	0	791.0	961.0	0.196	0.196	0.193	0.151	0.152	0.193	791.0	0.196	0.193	261.0	961.0	791.0	791.0	261.0	0.193	210.0	961.0	961.0	761.0
0.196	0.193	0.001	160'0	0.193	0.193	0.193	0.197	0	0.091	0.197	0.196	0.196	0.196	0.193	0.151	0.152	0.193	0.197	0.196	0.193	0.197	0.196	0.197	0.197	0.197	0.193	160'0	0.196	0.196	0.197
791.0	761.0	761.0	761.0	761.0	761.0	761.0	0	701.0	761.0	0.174	761.0	761.0	261.0	0.197	791.0	761.0	761.0	29010	761.0	761.0	0.117	761.0	0.126	29010	29010	761.0	761.0	761.0	761.0	0.18
0.196	0.144	0.193	0.193	0.144	0.159	0	0.197	0.193	0.193	0.197	0.196	0.196	0.196	0.144	0.193	0.193	0.144	0.197	0.196	0.19	0.197	0.196	0.197	0.197	0.197	0.144	0.193	0.196	0.196	0.197
0.196	0.159	0.193	0.193	0.159	0	0.159	0.197	0.193	0.193	0.197	0.196	0.196	0.196	0.159	0.193	0.193	0.159	0.197	0.196	0.19	761.0	0.196	0.197	0.197	761.0	0.159	0.193	0.196	0.196	761.0
961.0	0.098	0.193	0.193	0	0.159	0.144	761.0	0.193	0.193	261.0	961.0	0.196	0.196	0.043	0.193	0.193	0.083	761.0	0.196	0119	26110	0.196	261.0	761.0	261.0	0.05	0.193	961.0	0.196	761.0
0.196	0.193	0.09	0	0.193	0.193	0.193	0.197	0.091	0.09	0.197	0.196	0.196	0.196	0.193	0.151	0.152	0.193	0.197	0.196	0.193	0.197	0.196	0.197	0.197	0.197	0.193	0.09	0.196	0.196	0.197
0.196	0.193	0	0.09	0.193	0.193	0.193	0.197	0.091	210.0	0.197	0.196	0.196	0.196	0.193	0.151	0.152	0.193	0.197	0.196	0.193	0.197	0.196	0.197	0.197	0.197	0.193	970	0.196	0.196	0.197
0.196	0	0.193	0.193	0.098	0.159	0.144	701.0	0.193	0.193	761.0	0.196	0.196	0.196	0.098	0.193	0.193	0.098	701.0	0.196	010	791.0	0.196	761.0	761.0	761.0	0.098	0.193	0.196	0.196	701.0
0	0.196	0.196	0.196	0.196	0.196	0.196	0.197	0.196	0.196	0.197	0.107	0.186	0.107	0.196	0.196	0.196	0.196	0.197	0.107	0.196	0.197	0.107	0.197	0.197	0.197	0.196	0.196	0.135	0.167	0.197

Matrix I (b)

 $S=D^*$; The Satiated Minmax Matrix

> Matrix I (c) P* The satiated Minaddition matrix for P



Figure 3. (a) and (b): Polynomial approximations to $u(t_1)$ and $v(t_2)$ up to the fifth order (Errors shown in red)



Figure 4.

Page | 230

Progress of the approximation scheme from top left (Original Test Curve (Shown in bubbles) followed by its linear, quadratic, cubic, quartic and quintic approximations- from top left

3. SCOPE AND FUTURE STUDY

In the case when curves do not appear function-like, we could make an orthogonal transformation on the (x,y) co-ordinates to choose new co-ordinates for the points such that along one coordinate axis, there is maximum spread and along the other, a minimum spread. This is easily achieved by a suitable principal component analysis [PCA].Using the first PC score (ξ) as the 'independent' variable, one can fit the second PC score ' η ' as a function of ' ξ ', hopefully which can be a function. This latter approach can be very rewarding. This, of course can fail if the curve is a closed curve or a non-convex curve.

As already noted, in dealing with complex curves, for instance, self-intersecting curves, nonconvex curves or curves having cusps, the ordering of the points would be requiring more local information, particularly as one approaches across over point or a cusp. If one were to summarize curves as complex as in *figure1*, a global fit would be impossible; a piecewise approximation using parametric curves appears the only way out. Fitting parametric curves for each segment separately and then joining up the segments at the knots by adjusting derivatives of appropriate orders can be thought of, as is done in the case of splines.

It is also to be noted that this approach is applicable even to points in three or higher dimensional space where a meaningful distance metric can be defined so that Minmaxion becomes applicable. A tangentially relevant reference is [7] where the matrix operations are used to recognize patterns in a set of points.

REFERENCES

- [1] E.Cohen, R.F.Risenfled and G.Elber, Geometric Modelling with Splines, A.K. Peters, Massachusetts.
- [2] I.L.Dryden and K.V. Maridia, Statiatical Shape Analysis, John Wiley and sons, 1998.
- [3] V. A. K. Dutt, Multivariate and Related Statistical Methods in PatternRecognition, Ph.D. Thesis, Osmaina University, Htderabad, 1995.
- [4] S. N. N. Pandit, A new matrix calculus, Journal of the society of Industrial and Applied Mathematics, Vol.9 (1961), pp.632-639.
- [5] S. N. N. Pandit, Minaddition and an algorithm to find the most reliable paths in a network, I.R.E. Transactions on Circuit Theory,CT Vol.9 (1961),pp.190-191.
- [6] S. N. N. Pandit, Some quantitative Combinatorial Search Problems, Ph.D.Thesis, IIT, Kharagpur, 1963.
- [7] S. N. N. Pandit, V.V.Haragopal and G. Narasimha, Clump or Chain –an investigation into identifying and typing cluster of points with inter pointdistances, Proc. of A. P. Academy of Science, Vol.8 (4) pp.319-323, (October2004).
- [8] T.C.Reddy, On Routing and Related Problems, M.Phil. Dissertation, University of Hyderabad, 1998.
- [9] C.G.Small, the Statistical Theory of Shape, Springer, 1996.

AUTHORS' BIOGRAPHY



of interest.



Mr. Chillara Soma Shekar, born in 1974, is an Associate Professor in Mathematics. He obtained M. Sc., from Kakatiya University, Warangal, in 1997. He has 15 ½ years of experience in teaching of which 11 and half years are in Engineering and 4 years are in Junior colleges. He presently holds a faculty position at Bharat Institute of Engineering and Technology, Mangalpally, Hyderabad, Andhra Pradesh. He is ratified by JNTU Hyderabad. He held the position as Head of the Basic Sciences Department since 2002. He is pursuing doctoral degree under the guidance of Prof. Suri Ramamurthy, GRIET, Hyderabad in the areas of "Approximation theory and Pattern recognition". He has recently communicated some papers in his area

Dr. Ramamurthy Suri, born in 1961, is a Professor in Mathematics. He presently holds the appointment as Vice-Principal at Gokaraju Rangaraju Institute of Engineering and Technology, Kukatpally, Hyderabad, Andhra Pradesh. His earlier appointment in the same institute was Head of the Basic Sciences Department, which he held from the year 2001. He was awarded Doctoral degree from JNTUH, Hyderabad for his thesis "An adaptive algorithmic approach to problems in approximation theory" in the year 2007. He is currently supervising doctoral work in the areas of Approximation theory and Pattern recognition. Presently, his work is focused on defining new parametric descriptions of planar curves. He is a

passionate teacher and is also heading a research center at the same institute. He has published in a national journal and has recently communicated some papers in his area of interest.



Mr. SRK Reddy. Vemi Reddy, born in 1982, is an Assistant Professor in Mathematics. He presently holds the appointment at St. Mary's College of Enggineering and Technology, Hyderabad, Andhra Pradesh. He obtained M. Sc., from Kakatiya University, Warangal, in 2005. He has more than 9 years of teaching experience. He is pursuing Ph. D from Rayalaseema University, Kurnool, in the areas of "Approximation theory and Pattern recognition". He has recently communicated some papers in his area of interest